

# COMPLETELY REDUCIBLE SUBCOMPLEXES OF SPHERICAL BUILDINGS

CHRIS PARKER AND KATRIN TENT

In a spherical building  $\Delta$  two chambers in  $\Delta$  are *opposite* in  $\Delta$  provided their convex hull is an apartment of  $\Delta$ . Two simplices  $R$  and  $R'$  of  $\Delta$  are *opposite* in  $\Delta$  if for every chamber containing  $R$  there is an opposite chamber containing  $R'$ .

In 2005 Serre in [8] introduced the notion of complete reducibility in spherical buildings. He went on to point out the following conjecture [8, Conjecture 2.8] which he attributes to Tits from the 1950's.

**Conjecture 1** (Tits' Centre Conjecture). *Suppose that  $\Delta$  is a spherical building and  $\Omega$  is a convex subcomplex of  $\Delta$ . Then (at least) one of the following holds:*

- (a) *for each simplex  $A$  in  $\Omega$ , there is a simplex  $B$  in  $\Omega$  which is opposite to  $A$  in  $\Delta$ ; or*
- (b) *there exists a nontrivial simplex  $A'$  in  $\Omega$  fixed by any automorphism of  $\Delta$  stabilizing  $\Omega$ .*

If possibility (a) in the conjecture arises we say that  $\Omega$  is *completely reducible* and if (b) is the case, then the simplex  $A'$  is called a *centre* of  $\Omega$ . If alternative (a) holds then  $\Omega$  is a possibly thin subbuilding of  $\Delta$  (see [7]).

If  $G$  is an algebraic group with associated building  $\Delta$ , then a subgroup  $H$  of  $G$  is called *completely reducible* provided that whenever it is a subgroup of a parabolic subgroup of  $G$  it is contained in a Levi complement of that parabolic subgroup. In this case, the convex subcomplex of  $\Delta$  fixed by  $H$  is completely reducible. Conversely if the subcomplex of  $\Delta$  fixed by a subgroup  $H$  of a parabolic subgroup of  $G$  is completely reducible, then so is  $H$ . This relationship between complete reducibility of subcomplexes of the building and completely reducible subgroups of parabolic subgroups has lead to a source of fruitful research of which we particularly mention [1, Theorem 3.1] in which they prove the conjecture in the case that  $\Omega$  is the fixed point set of some subgroup  $H$ .

In the more general setting, for the classical buildings and buildings of rank 2 the conjecture was proved by Mühlherr and Tits [4] in 2006. For buildings of exceptional type  $E_6$ ,  $E_7$  and  $E_8$  the conjecture has been proved by Leeb and Ramos Cuevas [3, 6] using, in part, some of the observations presented by the authors at a meeting in Oberwolfach in January 2008 [5] and which now form the content of this note. They also include the proof of the conjecture for buildings of type

$F_4$ , which was first presented by the authors at that meeting. All of the investigations of the Centre Conjecture have used the lemma of Serre's [8] which states that  $\Omega$  is completely reducible if *every* vertex of  $\Omega$  has an opposite. For chamber complexes, we can prove the following stronger assertion and thereby obtain a very short proof of the Centre Conjecture for convex chamber subcomplexes of classical buildings.

**Theorem 2.** *Let  $\Delta$  be an irreducible spherical building of type  $(W, I)$ . Let  $\Omega$  be a convex chamber subcomplex of  $\Delta$ . If for some  $k \in I$  every vertex of type  $k$  in  $\Omega$  has an opposite in  $\Omega$ , then  $\Omega$  is completely reducible.*

Notice that the hypothesis that  $\Delta$  is irreducible in Theorem 2 may not be dropped as is easily seen by taking a product of two buildings and choosing a convex subcomplex which is completely reducible in one factor and has a centre in the second factor. Our notation follows [9]. So given a simplex  $R$  of type  $J \subseteq I$ , the collection of all simplices containing  $R$  form a building  $\text{St}R$  of type  $(W_{I \setminus J}, I \setminus J)$ . Of particular importance to us are the *projection maps*: given simplices  $R$  and  $S$ ,  $\text{proj}_R(S)$  is the unique simplex of  $\text{St}R$  which is contained in every shortest gallery from  $S$  to  $R$  (see [9, Proposition 2.29]) and is called the *projection* of  $S$  to  $R$ . Note that if  $\Omega$  is a convex subcomplex of  $\Delta$  then, for all simplices  $R$  and  $S$  in  $\Omega$ , we have  $\text{proj}_R S \in \Omega$  and this is the crucial property of convexity that we use in the proof of Theorem 2. We refer the reader to [9, 2.30 and 2.31] for many properties of projection maps.

**Lemma 3.** *Suppose that  $x$  and  $y$  are opposite chambers in  $\Delta$ . Let  $\Sigma$  be the convex hull of  $x$  and  $y$  in  $\Delta$  and  $R$  be a simplex in  $\Sigma$ . Then  $\text{proj}_R(x)$  and  $\text{proj}_R(y)$  are opposite in  $\text{St}R$ .*

*Proof.* Set  $x_1 = \text{proj}_R(x)$  and  $y_1 = \text{proj}_R(y)$ . Then  $x_1$  and  $y_1$  are chambers by [9, Proposition 2.29]. Let  $z$  be opposite  $x_1$  in  $\text{St}R$ . Then we have  $\text{dist}(x, z) = \text{dist}(x, x_1) + \text{dist}(x_1, z)$  and  $\text{dist}(y, z) = \text{dist}(y, y_1) + \text{dist}(y_1, z)$  by [9, 2.30.6]. Therefore  $\text{dist}(x, y) = \text{dist}(x, x_1) + \text{dist}(x_1, z) + \text{dist}(y_1, z) + \text{dist}(y, y_1)$  as every chamber of  $\Sigma$  is on a shortest gallery between  $x$  and  $y$  by [9, 2.35 (iv)]. On the other hand, as  $x_1$  and  $z$  are opposite in  $\text{St}R$ ,  $\text{dist}(x_1, y_1) \leq \text{dist}(x_1, z)$  and so

$$\begin{aligned} \text{dist}(x, y) &= \text{dist}(x, x_1) + \text{dist}(x_1, y_1) + \text{dist}(y_1, y) \\ &\leq \text{dist}(x, x_1) + \text{dist}(x_1, z) + \text{dist}(y, y_1). \end{aligned}$$

It follows that  $\text{dist}(y_1, z) = 0$  and hence  $z = y_1$  as claimed.  $\square$

The following observation is especially important to us.

**Corollary 4.** *Suppose that  $R$ ,  $X$  and  $Y$  are simplices in the apartment  $\Sigma$  with  $X$  opposite  $Y$ . Then either*

- (a)  $\text{proj}_R(X)$  is opposite  $\text{proj}_R(Y)$  in  $\text{St}R$ ; or

(b)  $R = \text{proj}_R(X) = \text{proj}_R(Y)$ .

*Proof.* We can pair the chambers containing  $X$  and  $Y$  into opposite pairs  $(x, y)$ . Then  $\text{proj}_R(x)$  is opposite  $\text{proj}_R(y)$  in  $\text{St}R$  by Lemma 3. This means every chamber of  $\text{proj}_R(X)$  has an opposite in  $\text{St}R$  contained in  $\text{proj}_R(Y)$ .  $\square$

We can now prove Theorem 2. So suppose that  $\Omega$  is a convex chamber subcomplex of  $\Delta$ . Recall that we say  $\Omega$  is a chamber complex if every simplex is contained in a chamber and if all the faces of every simplex of  $\Omega$  are contained in  $\Omega$ .

We repeatedly use the fact that, as  $\Omega$  is convex, projections between simplices of  $\Omega$  are contained in  $\Omega$ .

By hypothesis, we may choose  $J \subseteq I$  maximally so that every simplex of type  $J$  in  $\Omega$  has an opposite in  $\Omega$ . It suffices to show that  $J = I$ , as, if a chamber has an opposite, then so does every face of that chamber. So suppose that  $J \neq I$ . Since  $\Delta$  is irreducible there is  $i \in I \setminus J$  such that  $i$  is a neighbour of some  $j \in J$  in the Dynkin diagram of  $\Delta$ .

Let  $z$  be of type  $J \cup \{i\}$  in  $\Omega$ ,  $x_0$  be the face of  $z$  of type  $J$ ,  $\ell$  the vertex of  $z$  of type  $i$  and let  $C_0$  be a chamber of  $\Omega$  containing  $z$ . We will construct an opposite for  $z$ .

Let  $p$  be a maximal face of  $C_0$  with missing vertex of type  $j$  and  $x_0^o$  be an opposite of  $x_0$  in  $\Omega$ . Then  $\ell$  is a vertex of  $p$ . Put  $C'_0 = \text{proj}_{x_0^o} C_0$  and  $C_1 = \text{proj}_p C'_0$ . Then, by Corollary 4,  $C_0 = \text{proj}_p(x_0) \neq C_1$ . Let  $x_1$  be the face of  $C_1$  of type  $J$ . So  $x_1 \neq x_0$  and setting  $y_0 = \text{proj}_{x_1} x_0$  we see that, as the reflections corresponding to  $i$  and  $j$  do not commute,  $y_0$  has  $x_1$  as a face and  $\ell$  as a vertex. We will first find an opposite of the simplex  $y_0$ .

Let  $y_1 = \text{proj}_{x_1} x_0^o$ , so  $y_1$  and  $y_0$  are opposite in  $\text{St}x_1$  by Corollary 4. Let  $x_1^o$  be opposite  $x_1$ . By [9, Proposition 3.29], we have  $y_2 = \text{proj}_{x_1^o}(y_1)$  is opposite  $y_0$ . Since  $y_0$  contains the vertex  $\ell$ ,  $y_2$  has an opposite of  $\ell$  as a vertex and this is contained in  $\Omega$ .

In order to find an opposite for the simplex  $z$ , notice that  $\text{proj}_\ell x_0 = z$ . Let  $z_1 = \text{proj}_\ell x_0^o$ , so  $z_1$  and  $z$  are opposite in  $\text{St}\ell$  by Corollary 4. Using [9, Proposition 3.29] again, the projection of  $z_1$  to the opposite of  $\ell$  in  $\text{St}y_2$  now yields the required opposite of  $z$  in  $\Omega$ .  $\square$

**Corollary 5.** *The Centre Conjecture holds for convex chamber subcomplexes of irreducible spherical buildings of classical type.*

*Proof.* For buildings of type  $A_n, B_n, C_n$  and  $D_n$ , we identify the simplices of  $\Delta$  with flags of subspaces (singular subspaces, isotropic subspaces) in the appropriate vector spaces. We then consider the vertices of  $\Delta$  corresponding to

1-dimensional subspaces (for  $A_n$ ) and 1-dimensional isotropic/singular subspaces in the other cases and call them type 1 vertices.

Since  $\Omega$  is a chamber subcomplex,  $\Omega$  contains vertices of every type. If every type 1 vertex has an opposite in  $\Omega$ , then  $\Omega$  is completely reducible by Theorem 2. So we suppose that this is not the case and aim to identify a centre.

Suppose that  $\Delta$  has type  $A_n$  and assume that some type 1 vertex  $w$  of  $\Omega$  does not have an opposite in  $\Omega$ . Then  $w$  is contained in all the hyperplanes of  $\Omega$ . Thus the intersection of all hyperplanes of  $\Omega$  is the required centre.

Suppose that  $\Delta$  has type  $B_n, C_n$  or  $D_n$ . Then a vertex of type 1 in  $\Omega$  has no opposite in  $\Omega$  if and only if it is collinear with every other vertex of type 1 in  $\Omega$ . Hence the set of all vertices of type 1 in  $\Omega$  having no opposite span a totally isotropic (singular) subspace, and this is the centre.  $\square$

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CHRIS PARKER, SCHOOL OF MATHEMATICS, UNIVERSITY OF BIRMINGHAM, EDGBASTON, BIRMINGHAM B15 2TT, UNITED KINGDOM

*E-mail address:* `c.w.parker@bham.ac.uk`

KATRIN TENT, MATHEMATISCHES INSTITUT, UNIVERSITÄT MÜNSTER, EINSTEINSTRASSE 62, 48149 MÜNSTER, GERMANY

*E-mail address:* `tent@uni-muenster.de`