

Thread-Modular Shape Analysis

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Programs and Properties

- Concurrent programs
- Unbounded number of threads
 - parametric systems
- Unbounded number of objects
- Pointers and destructive updates
- Memory safety
 - Absence of null dereferences
 - Absence of memory leaks
- Preservation of data structure invariants
- Linearizability
- User-specified invariants

Concurrent Set [M. Maged SPAA'02]

```
remove(key) {
  while (true) {
    <prev,cur,next,found> = locate(key)
    if (!found) return false;
    if (CAS(prev.next, <0,cur>, <0,next>))
      DeleteNode(curr2);
    if (!CAS(cur.next, <0,next>, <1,next>))
      continue;
    else locate(key);
  }
}
```

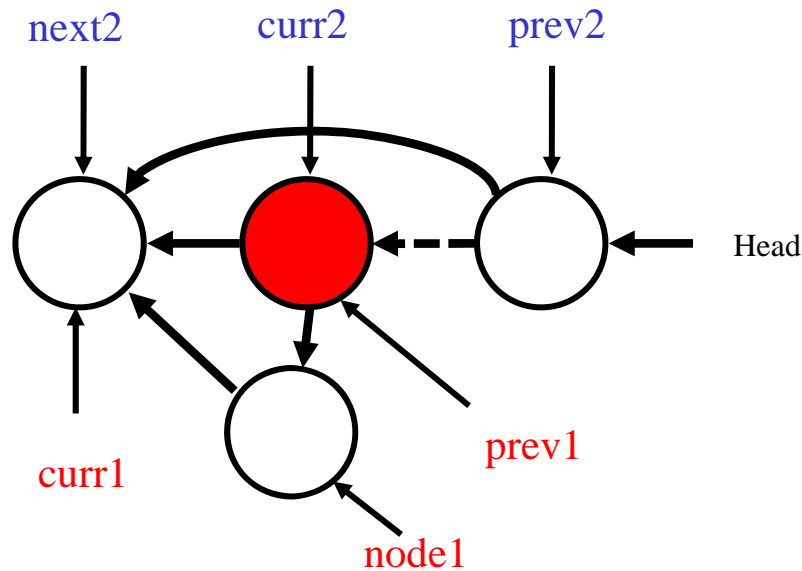
```
add(node) {
  while (true) {
    <prev,cur,next,found> = locate(node.key)
    if (found) return false;
    node.next = cur
    if (CAS(prev.next, <0,cur>, <0,node>))
      return true;
  }
}
```

```
locate(key) {
  restart: pred = Head ;
  <tmp,curr> = pred.next;
  while (true) {
    if (curr == null) return <null, null, null, false>;
    <cmark, next> = curr.next;
    ckey = curr.key;
    if (pred.next != <0,curr>) goto restart;
    if (!cmark) {
      if (ckey >= key) return <prev, curr, next, (key == ckey) >
      pred = curr;
    }
    else { if (CAS(pred.next, <0,curr>, <0,next>)) DeleteNode(curr);
           else goto restart; }
    curr = next; }
}
```

Concurrent Set [M. Maged SPAA'02]

```
remove(key) {  
  while (true) {  
    <prev2,cur2,next2,found> = locate(key)  
    if (!found) return false;  
    if (CAS(prev2.next, <0,curr2>, <0,next2>))  
      DeleteNode(cur2);  
    if (!CAS(cur2.next, <0,next2>, <1,next2>))  
      continue;  
    else locate(key);  
  }  
}
```

```
add(node1) {  
  while (true) {  
    <prev,cur,next,found> = locate(node1.key)  
    if (found) return false;  
    node1.next = cur1  
    if (CAS(prev1.next, <0,cur1>, <0,node1>))  
      return true;  
  }  
}
```




 A memory leak

What is the bug?

- A node is removed before it is marked

```
remove(key) {  
  while (true) {  
    <prev,cur,next,found> = locate(key)  
    if (!found) return false;  
    if (!CAS(cur.next, <0,next>, <0,next>))  
      continue;  
    if (CAS(prev.next, <0,cur>, <1,next>))  
      DeleteNode(cur);  
    else locate(key);  
  }  
}
```



```

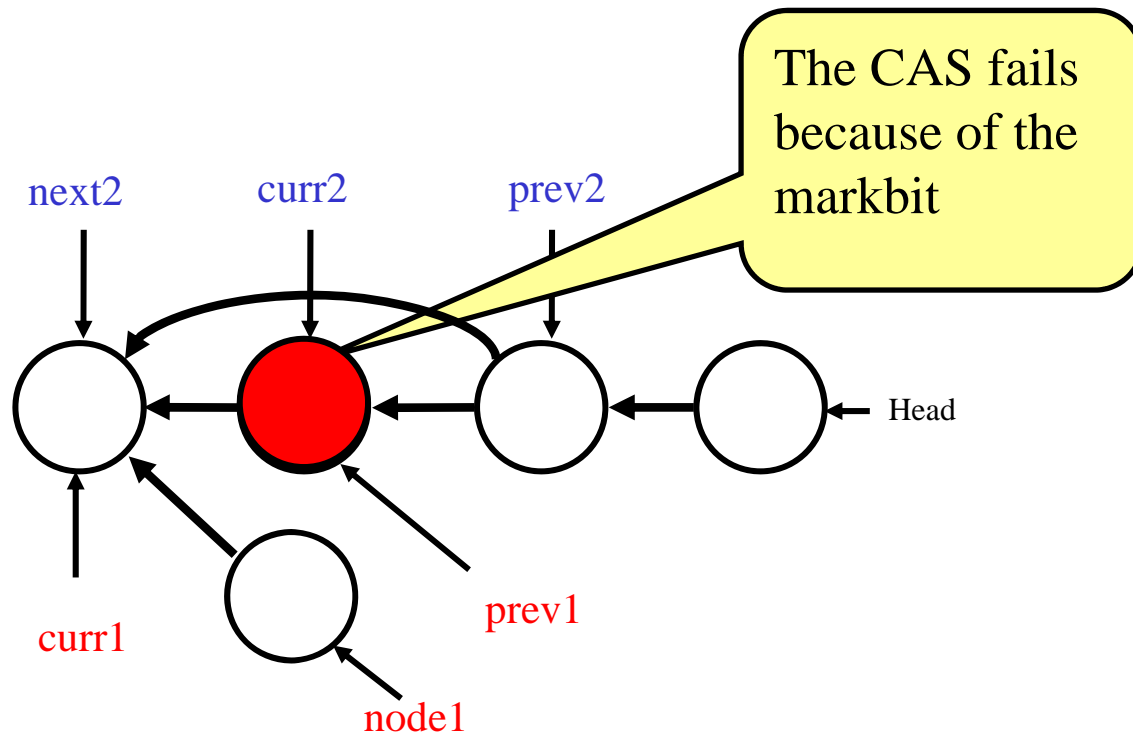
remove(key) {
  while (true) {
    <prev2,cur2,next2,found> = locate(key)
    if (!found) return false;
    if (!CAS(cur2.next, <0,next2>, <1,next2>))
      continue;
    if (CAS(prev2.next,<0,cur2>, <0,next2>))
      DeleteNode(curr2);
    else locate(key);
  }
}

```

```

add(node1) {
  while (true) {
    <prev1,cur1,next1,found>=locate(node1.key)
    if (found) return false;
    node1.next = curr1
    if (CAS(prev1.next, <0,curr1>, <0,node1>))
      return true;
  }
}

```



Captured Invariants

- No memory leaks
 - Every “dangling” pointer is pointed-to by some thread reachable from **Head**, or has been returned by some remove method
- After a successful add, **prev** is reachable from **Head**, the node inserted is pointed-to by **prev** and it points to **curr**
- Only a single node can be added/removed by each operation
- An outgoing edge of a marked node is immutable

Challenges

- Develop an analysis which automatically proves interesting properties of concurrent heap-manipulating programs
 - Concurrency is challenging
 - The global nature of the heap
- Designing the right abstraction
- Developing effective transformers
 - Sound proof rules for atomic statements

A Singleton Buffer

Boolean empty = true;

Object b = null;

```
produce() {  
  1: Object p = new();  
  2: await (empty) then {  
    b = p;  
    empty = false;  
  }  
  3:  
}
```

```
consume() {  
  Object c;  
  4: await (!empty) then {  
    c = b;  
    empty = true;  
  }  
  5: use(c);  
  6: dispose(c);  
  7:  
}
```

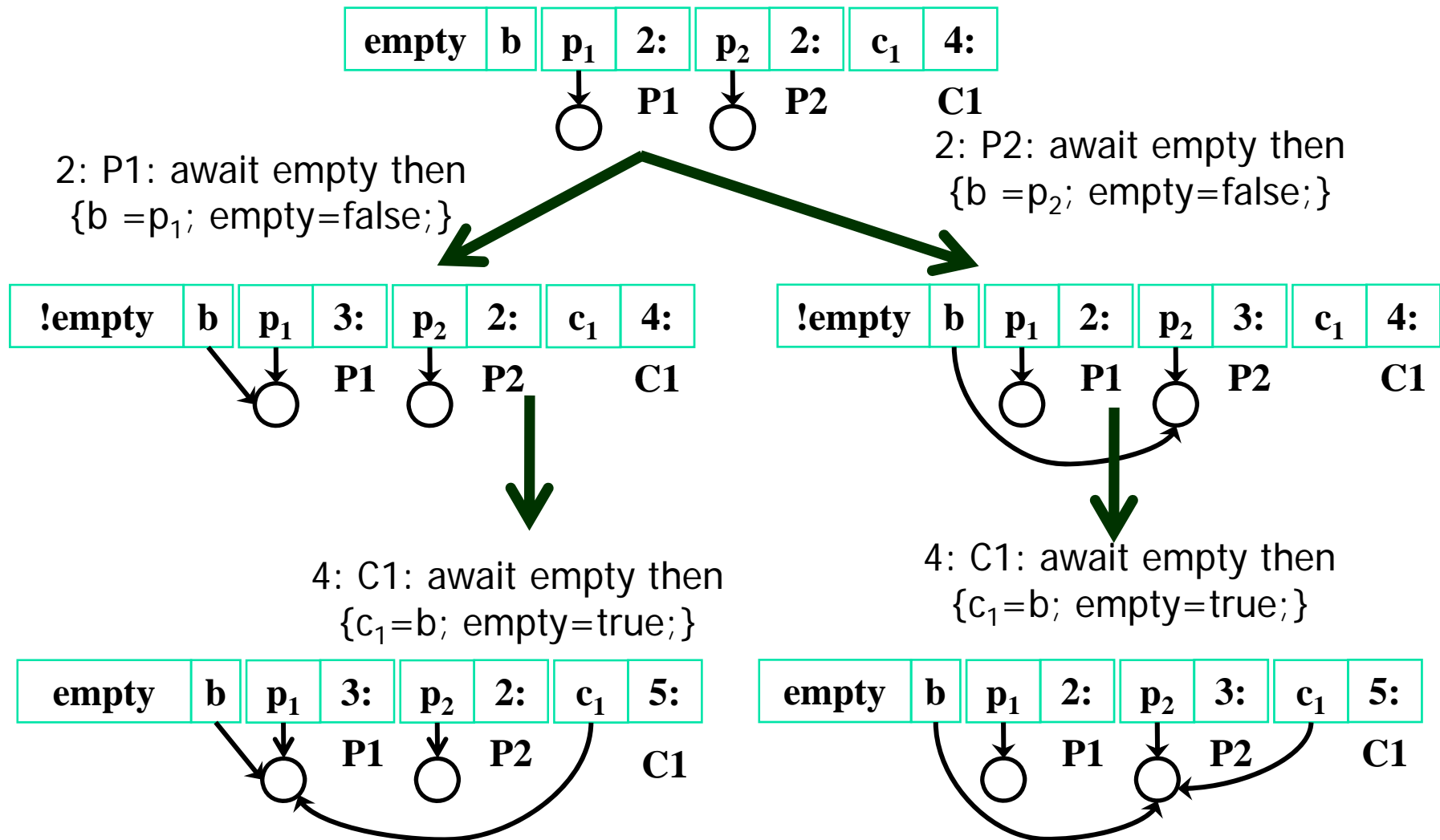
Safe
Dereference

No
Double free

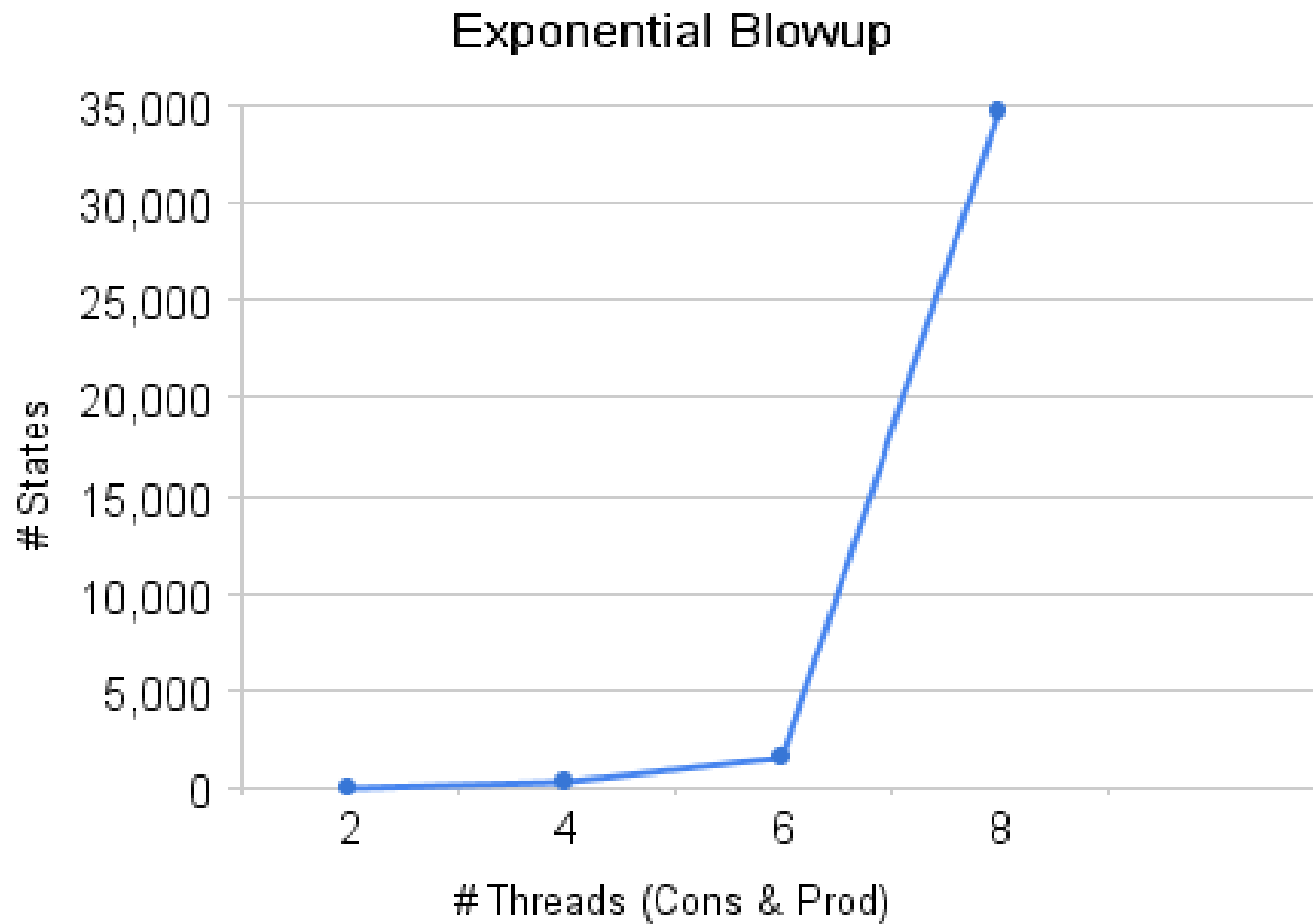
State Space Exploration

- Enumerate all interleavings
- Check the properties

Partial State Space Exploration 1 consumer/2 producers



State Space Explosion (bounded number of threads)



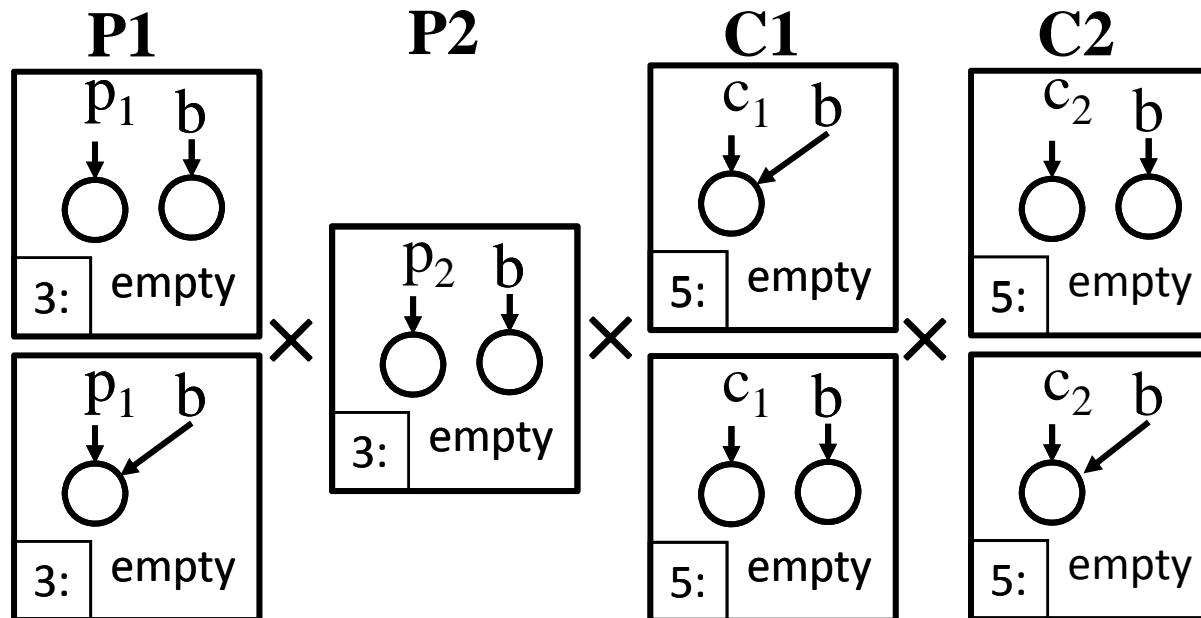
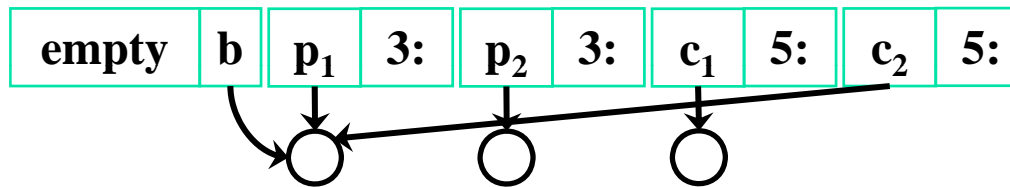
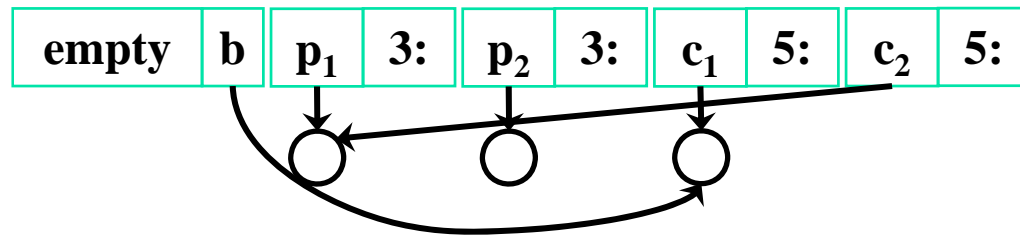
Plan

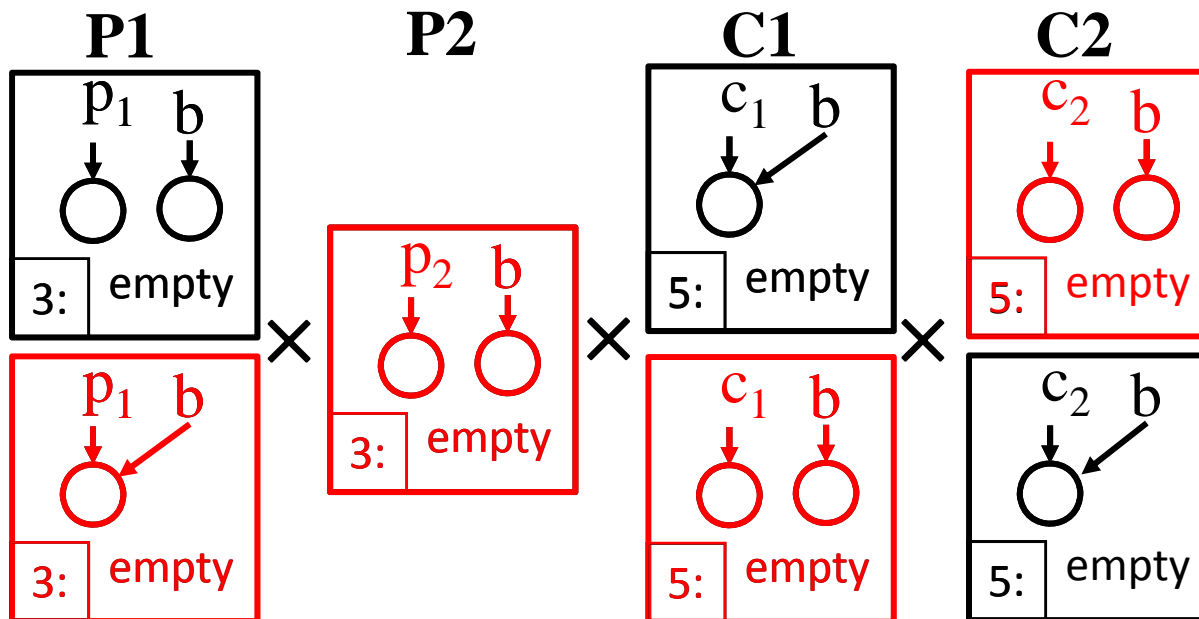
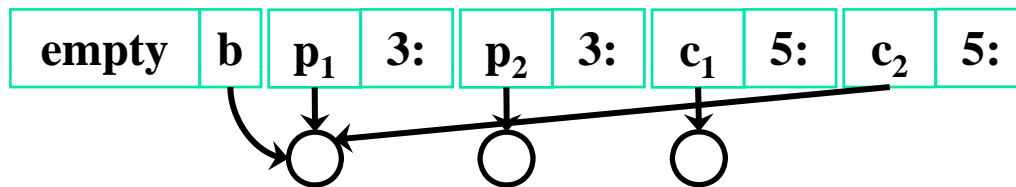
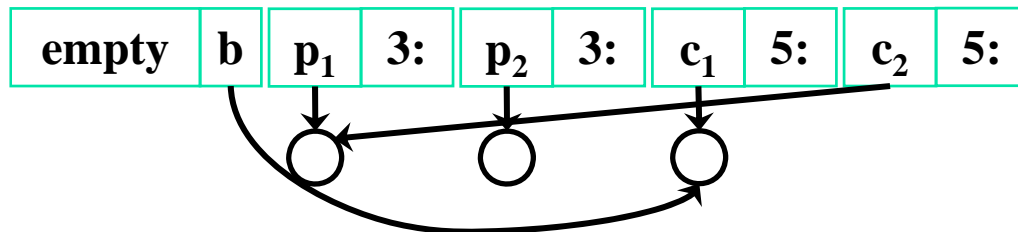
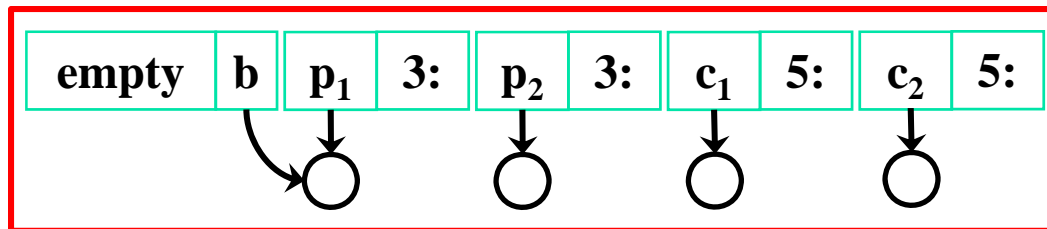
- Thread-modular analysis
- Semi-thread-modular analysis
- Unbounded number of threads
- Empirical results

Thread-Modular Analysis

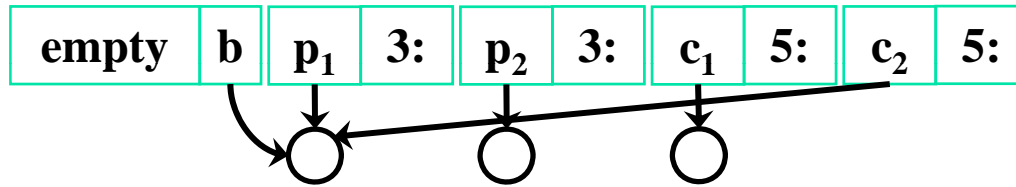
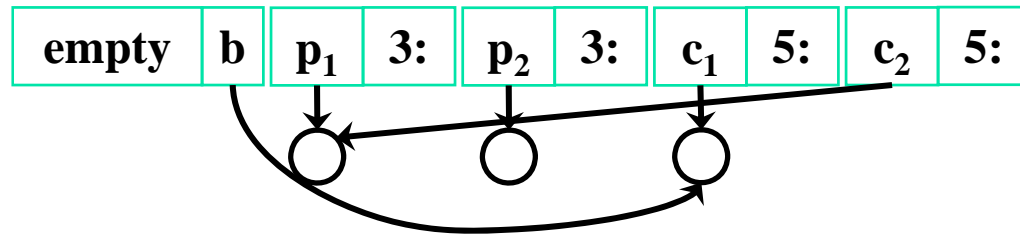
- Abstract away the correlations between local states of different threads
 - No correlations between program counters
 - Cartesian Abstraction
- Information maintained
 - Correlations between the local state and global state of each thread
- “The quadratic cost of computing transformers can be greatly reduced...”
[Flanagan & Qadeer SPIN, 2003]
- Naturally handles unbounded number of threads

Thread-Modular Abstraction

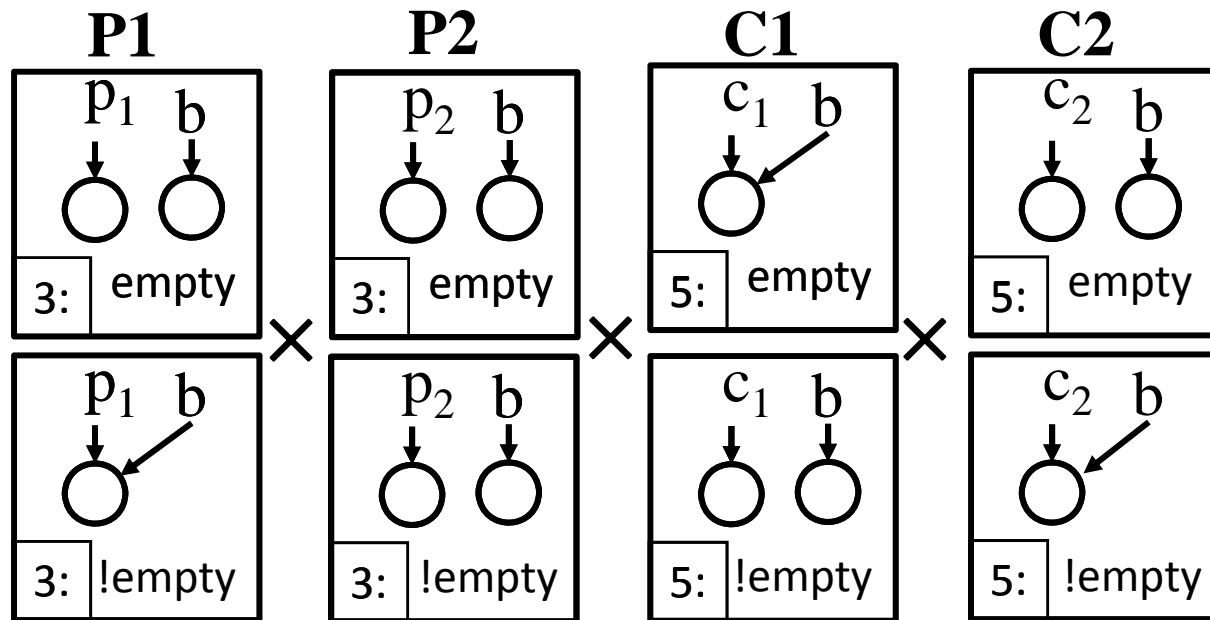




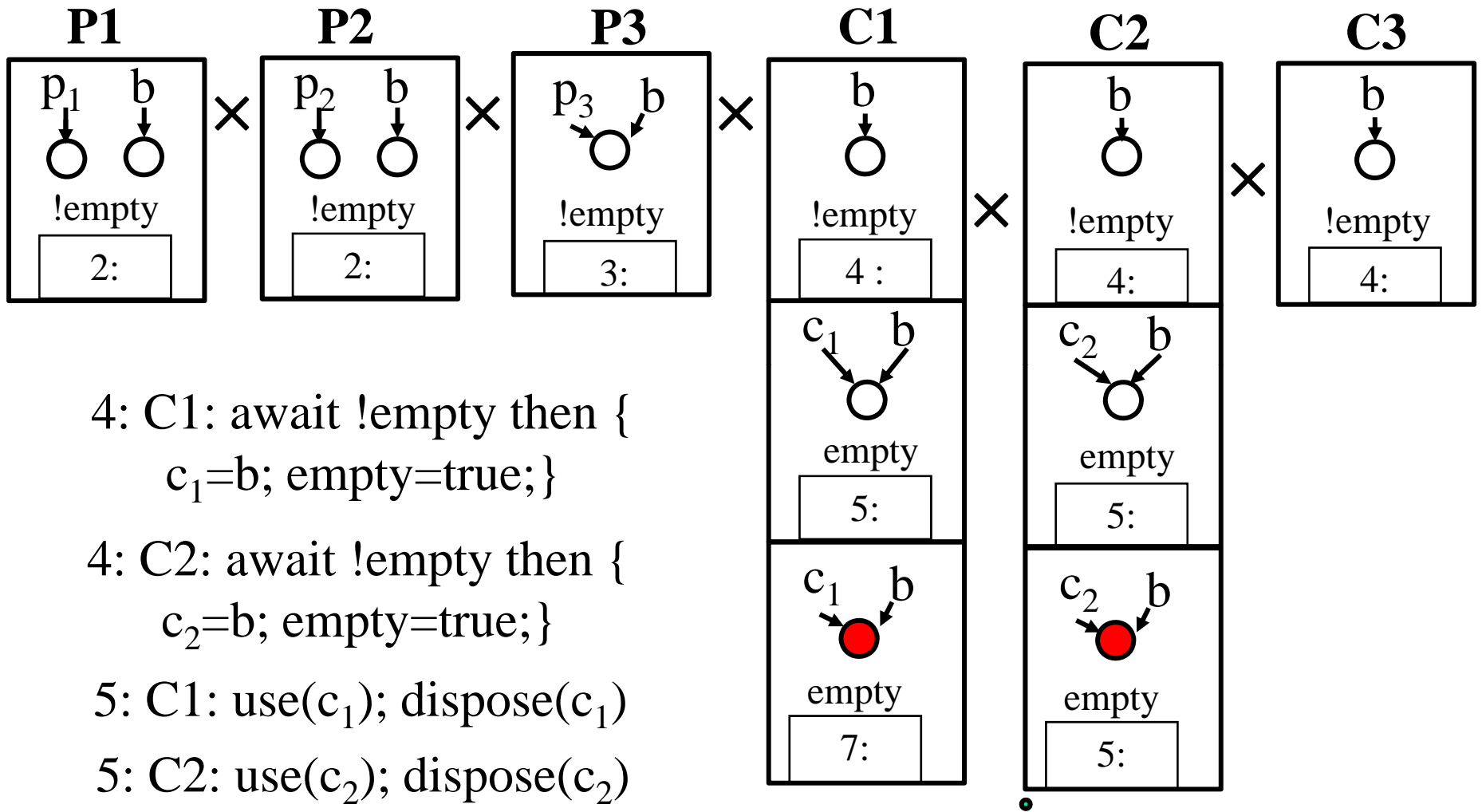
Thread-Modular Abstraction



not all combinations are feasible



Partial Abstract Interpretation



4: C1: await !empty then {
 $c_1=b$; empty=true;}

4: C2: await !empty then {
 $c_2=b$; empty=true;}

5: C1: use(c_1); dispose(c_1)

5: C2: use(c_2); dispose(c_2)

**Potential
 Double Free!!!**

A Singleton Buffer

Boolean empty = true;

Object b = null;

```
produce() {  
  1: Object p = new();  
  2: await (empty) then {  
    b = p;  
    empty = false;  
  }  
  3:  
}
```

```
consume() {  
  Object c;  
  4: await (!empty) then {  
    c = b;  b=null;  
    empty = true;  
  }  
  5: use(c);  
  6: dispose(c);  
  7:  
}
```

Safe
Dereference

No
Double free

Thread-Modular Analysis

- Abstract away the correlations between local states of different threads
 - No correlations between program counters
 - Cartesian Abstraction
- Information maintained
 - Correlations between the local state of each thread and the global state
- Scales with the number of threads
- Handles unbounded number of threads
- But limited precision

Increasing Precision

- Enforce program restrictions
 - Limited aliasing
 - Ownership relations [Boyapati et. al. OOPSLA'02]
 - Limited concurrency
- Enhanced analysis
 - Global instrumentation
 - Separation Domains [Gotsman et. al. PLDI'07]
 - Semi-Thread Modular Analysis [Berdine et. al. CAV'08, Segalov et. al., TR]

Microsoft Development Environment [design] - kbdclass.c [Read Only]

File Edit View Debug Tools Window Help

kbdclass.c

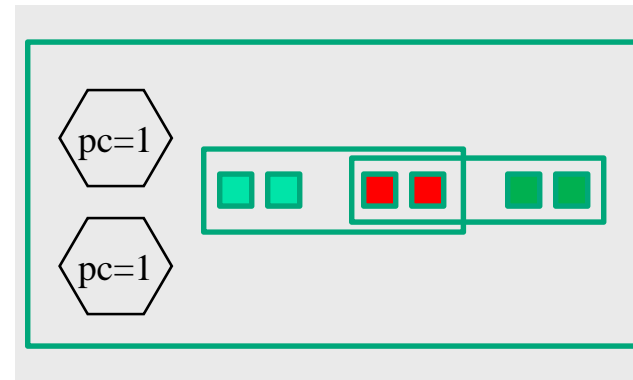
```
987 {
988     PIRP irp;
989     LIST_ENTRY listHead, *entry;
990     KIRQL irql;
991
992     InitializeListHead(&listHead);
993
994     KeAcquireSpinLock(&DeviceExtension->SpinLock, &irql);
995
996     do {
997         irp = KeyboardClassDequeueReadByFileObject(DeviceExtension, FileObject);
998         if (irp) {
999             irp->IoStatus.Status = STATUS_CANCELLED;
1000             irp->IoStatus.Information = 0;
1001
1002             InsertTailList (&listHead, &irp->Tail.Overlay.ListEntry);
1003         }
1004     } while (irp != NULL);
1005
1006     KeReleaseSpinLock(&DeviceExtension->SpinLock, irql);
1007
1008     //
1009     // Complete these irps outside of the spin lock
1010     //
1011     while (! IsListEmpty (&listHead)) {
1012         entry = RemoveHeadList (&listHead);
1013         irp = CONTAINING_RECORD (entry, IRP, Tail.Overlay.ListEntry);
```

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Thread-Modular Analysis

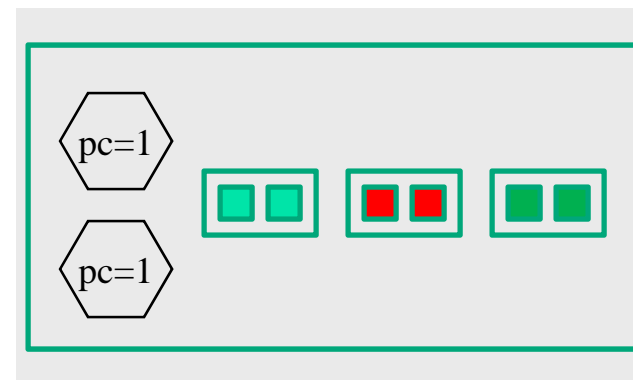
Non-disjoint resource invariants
[the rest of this talk]

Fine-grained concurrency

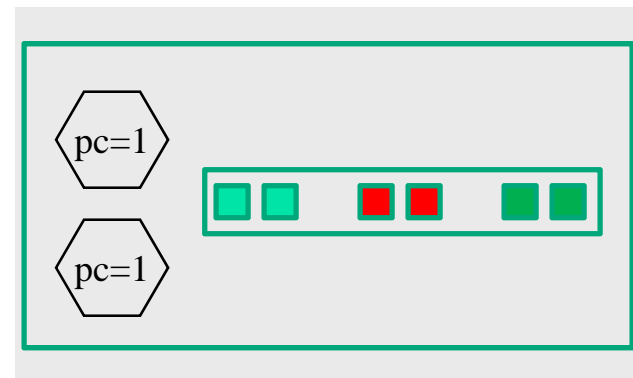


Separated resource invariants
[Gotsman et al., PLDI 07]

Coarse-grained concurrency



Single global resource invariant
[Flanagan & Qadeer, SPIN 03]



Thread Quantification for Concurrent Shape Analysis

J. Berdine, T. Lev-Ami, R. Manevich, G. Ramalingam, M. Sagiv

CAV'08

Semi-Thread-Modular Analysis

M. Segalov, T. Lev-Ami, R. Manevich, G. Ramalingam, M. Sagiv

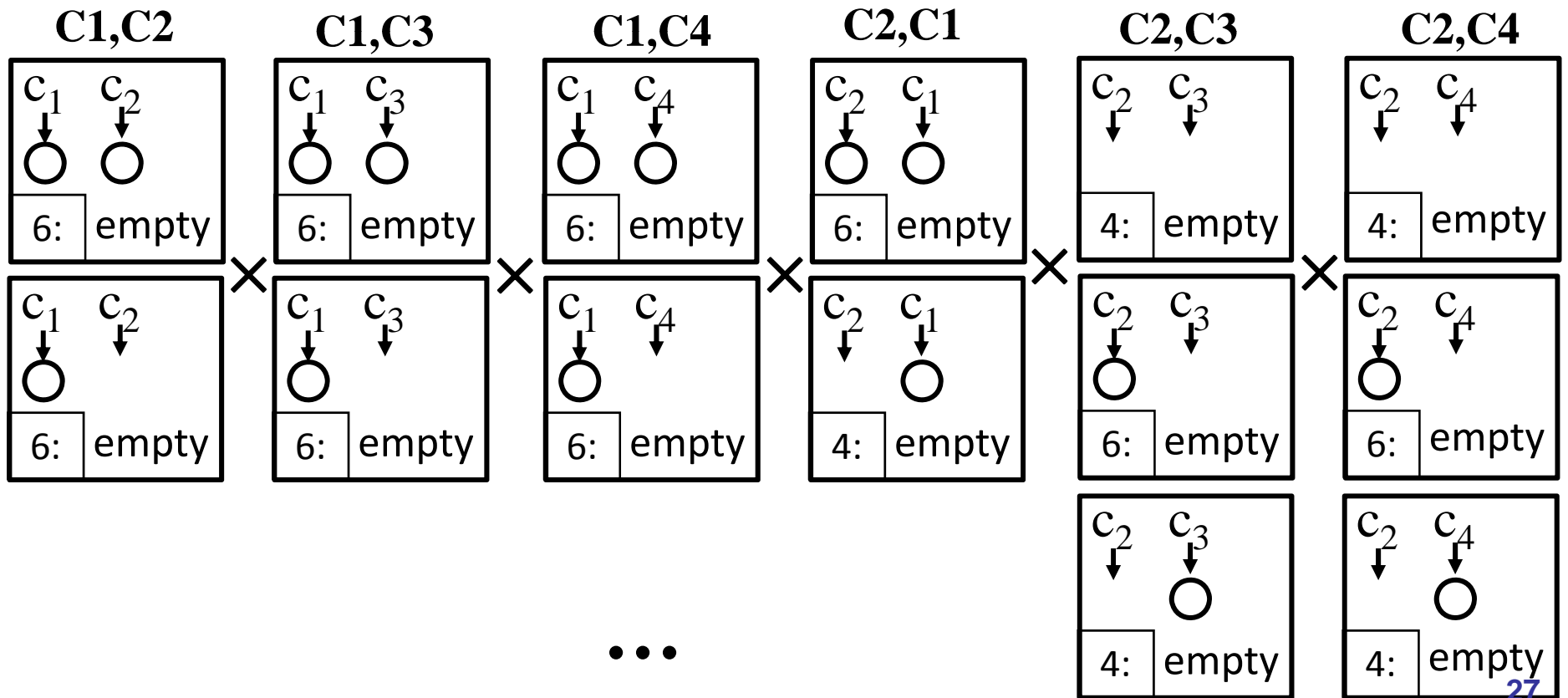
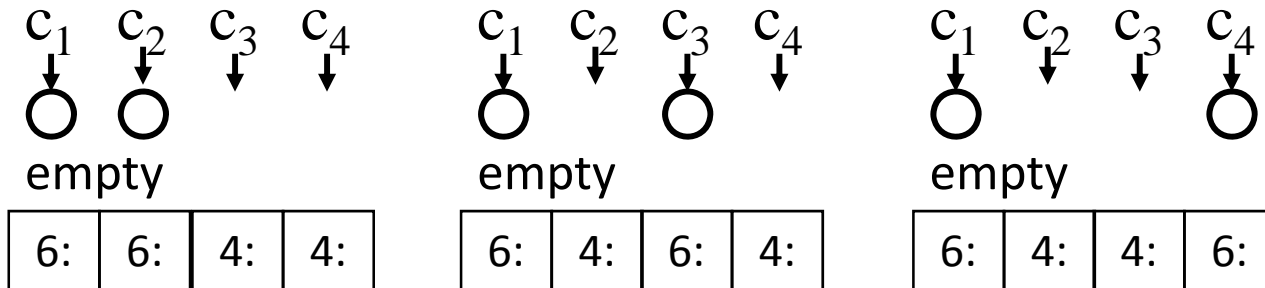
Main Results

- A refinement of thread-modular analysis
 - Not fully modular
- Precise enough to prove properties of fine-grained concurrent programs
 - Were not automatically proved before
- Two effective methods for efficiently computing transformers
 - Summarizing Effects
 - Summarizing Abstraction
 - On a concurrent set imp. speedup is x34!

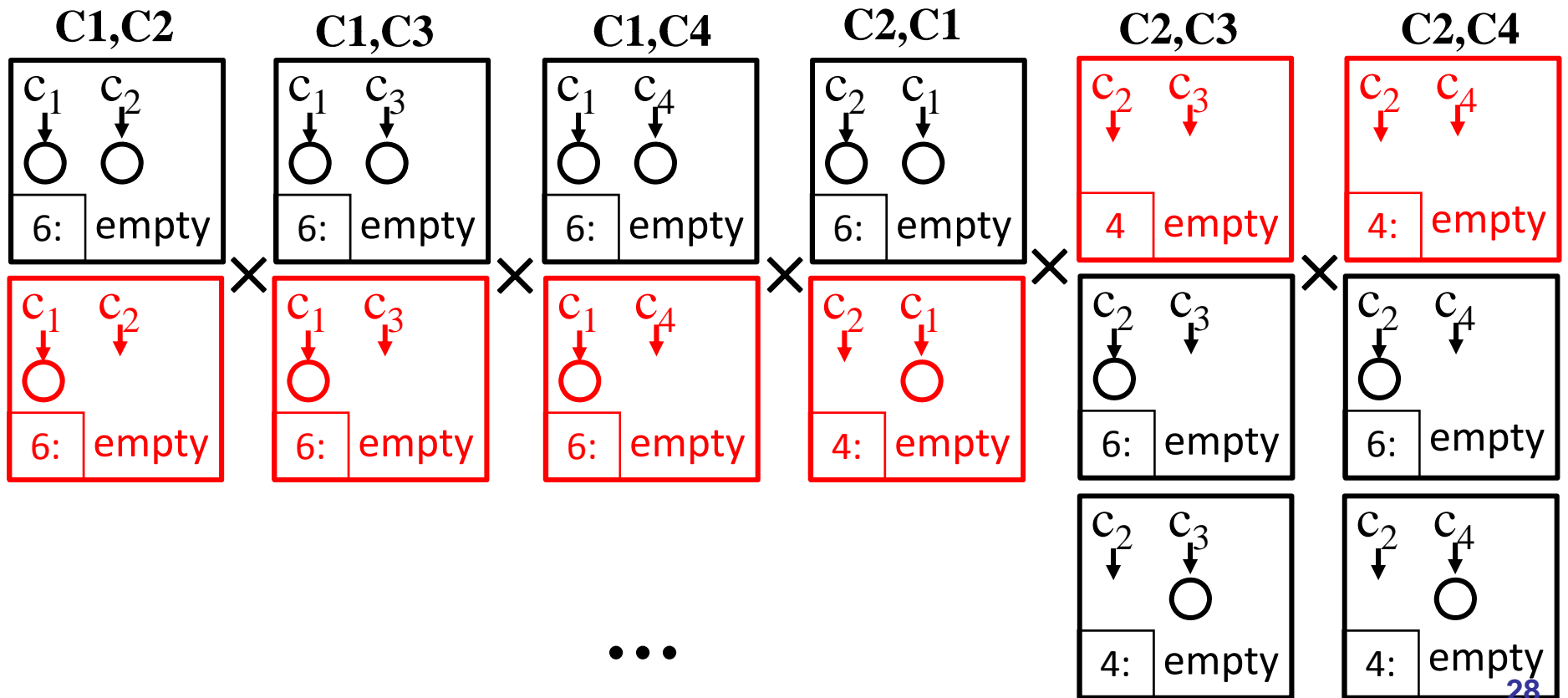
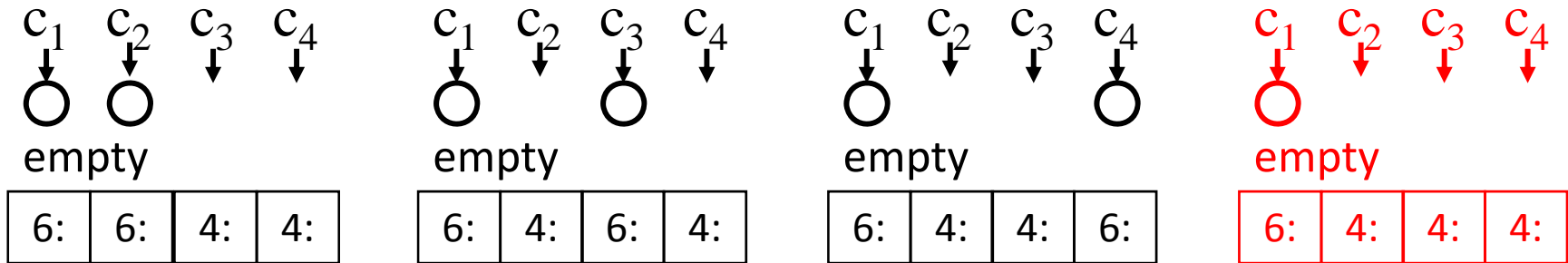
Semi-Thread-Modular Analysis

- Abstract away correlations between local states of more than two threads
- Information maintained
 - Correlations between the local state of each thread and the global state
 - May-correlations between local states of every pair of threads
 - Not necessarily symmetric

Semi-Thread-Modular Abstraction



Semi-Thread-Modular Concretization



Worst-Case Complexity

- Full state analysis

- Shared state – G , Local state – L_{tid}
- State space = $\wp(G \times L_1 \times \dots \times L_n)$
- #states: $O(|G| \cdot |L|^n)$

- Thread-modular analysis

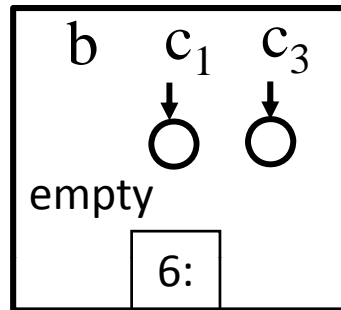
- State space = $\wp(G \times L_1) \times \dots \times \wp(G \times L_n)$
- #states: $O(n \cdot |G| \cdot |L|)$

- Semi-thread-modular analysis

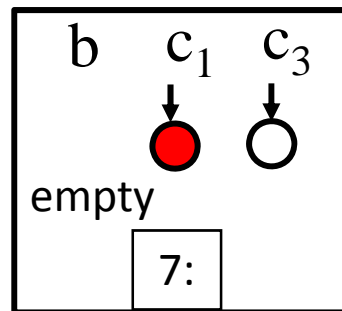
- State space = $\wp(G \times L_1 \times L_2) \times \dots \times \wp(G \times L_{n-1} \times L_n)$
- #states: $O(n \cdot |G| \cdot |L|^2)$

Point-wise Transformer

6: C1: dispose(c_1)

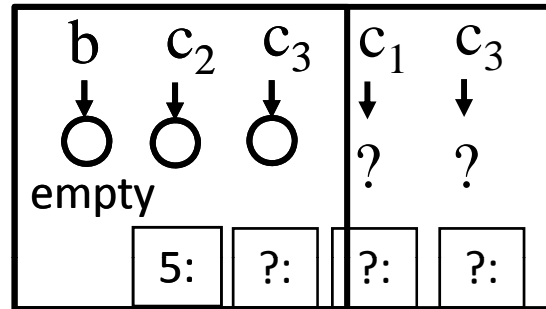


6: C1: dispose(c_1)



Point-wise Transformer

6: C1: dispose(c₁)



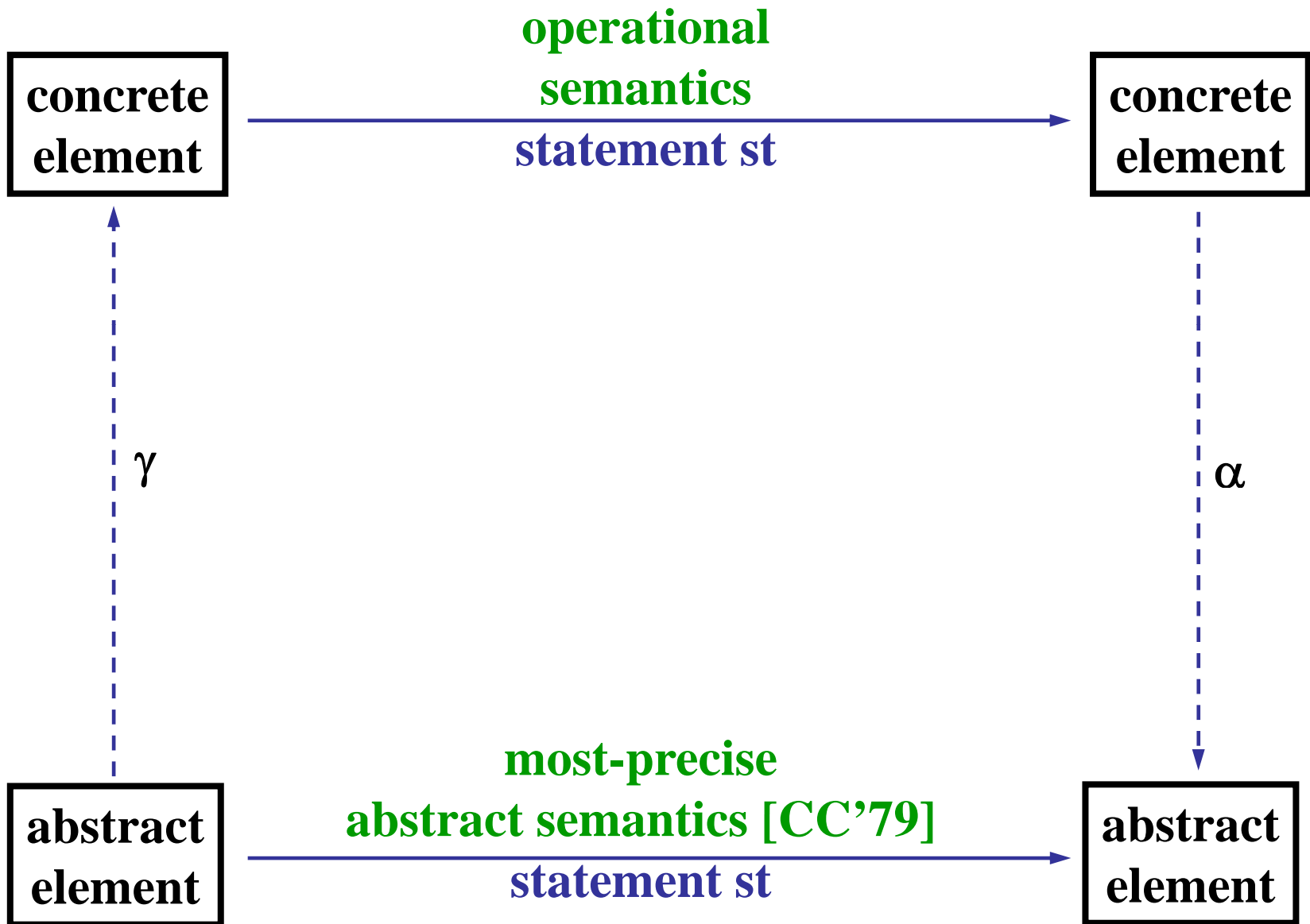
6: C1: dispose(c₁)

Is this command safe in this configuration?

Missing information on c₁

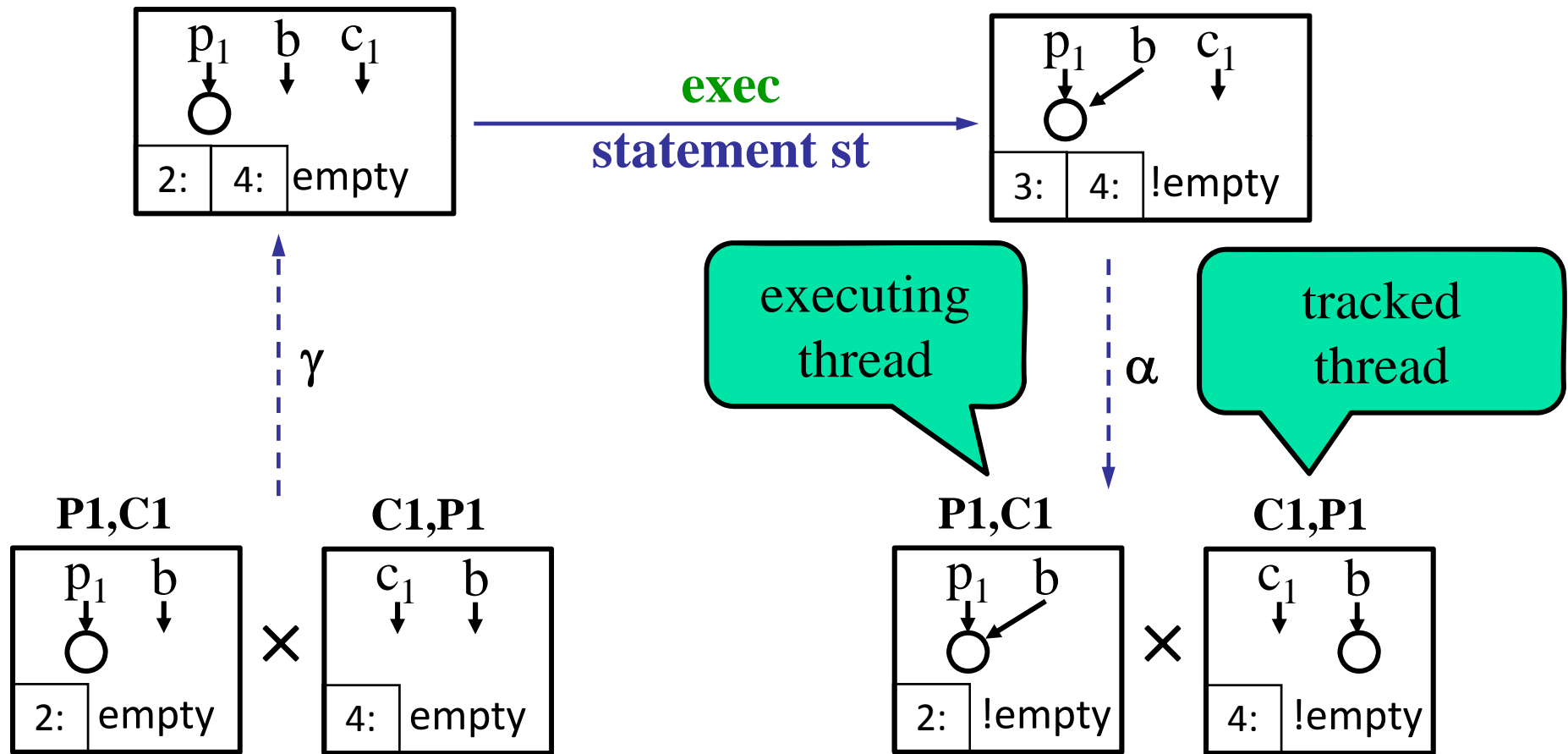
Unknown effect on b

Most-Precise Transformer

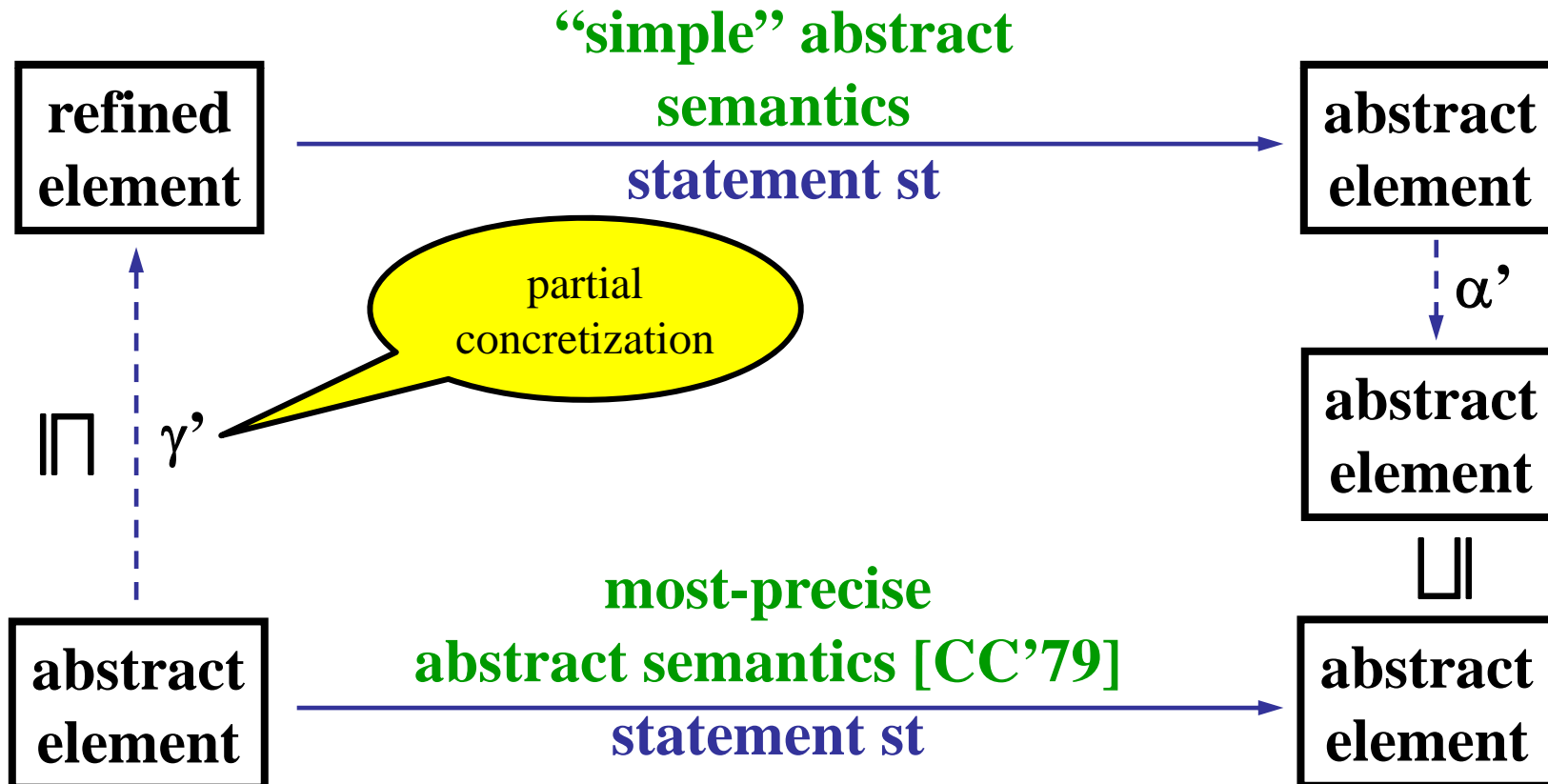


Most-precise transformer

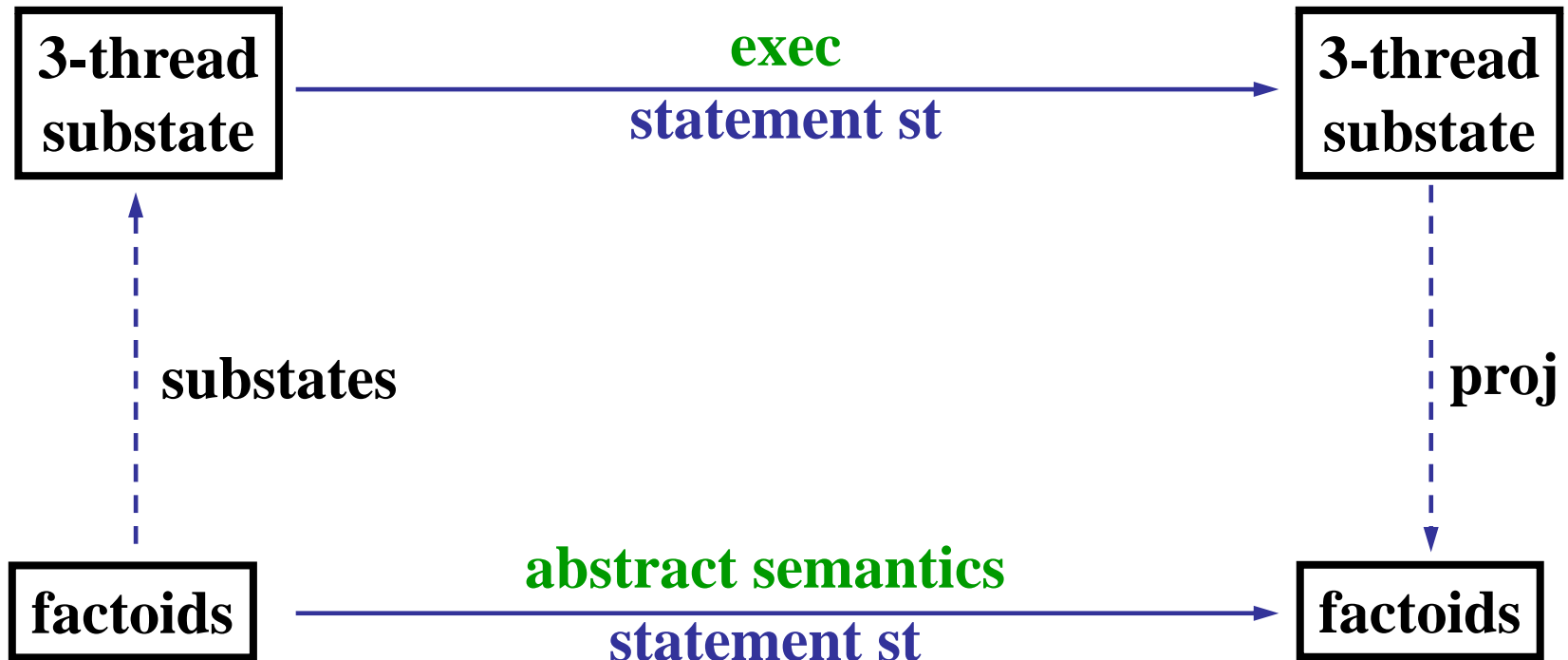
2: P1: await (empty) then { b=p₁; empty=false; }



Sound Transformer



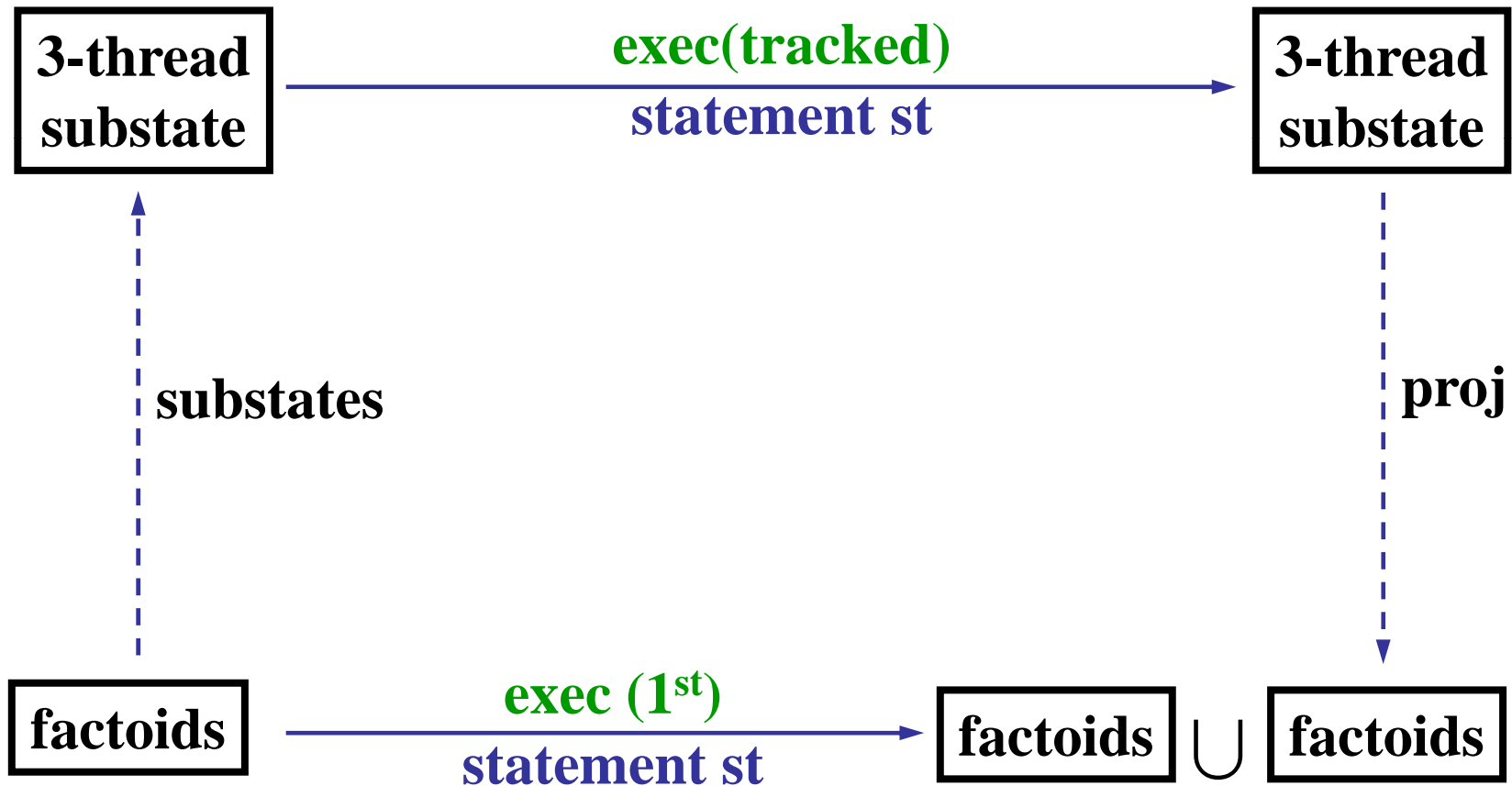
Partial Concretization-based Transformer



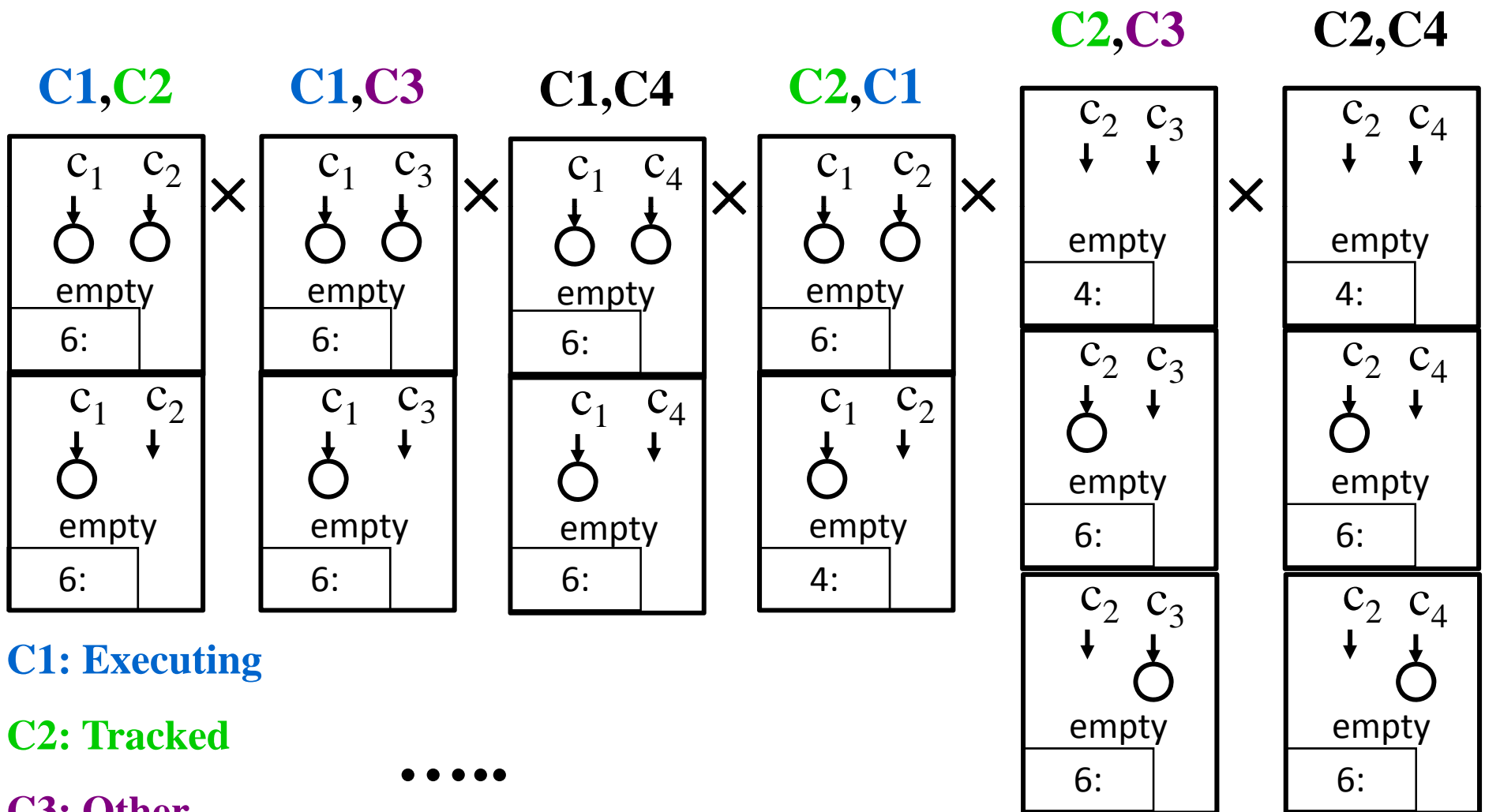
Transformer for Concurrent Systems

$$\text{TR}(F) = \{ \langle l', g', o \rangle : \langle l, g, o \rangle \in F, \langle l, g \rangle \tau \langle l', g' \rangle \}$$

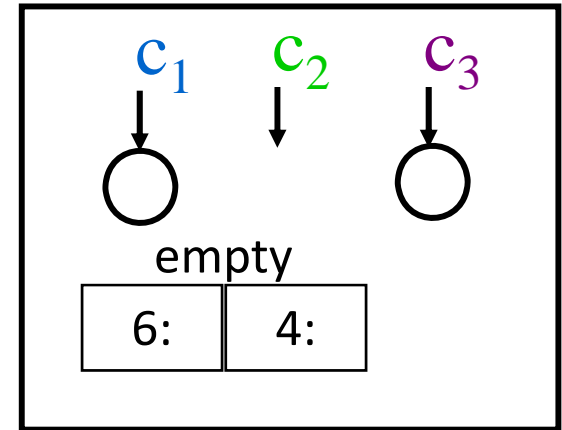
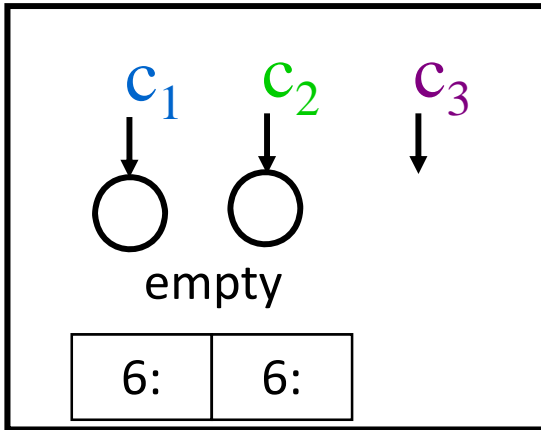
$$\cup \left\{ \begin{array}{l} \langle l_2, g', o \rangle, \langle l_2, g', \alpha(l_1') \rangle : f_1, f_2, f_3, f_4 \in F: \\ \langle l_1, g, l_2, o \rangle \in \text{substates}(f_1, f_2, f_3, f_4), \\ \langle l_1, g \rangle \tau \langle l_1', g' \rangle \end{array} \right\}$$



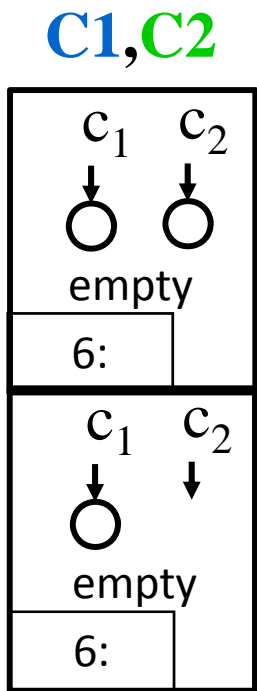
Partial Concretization



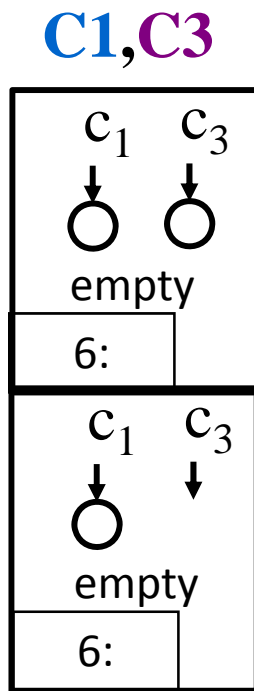
Partial Concretization(Substates)



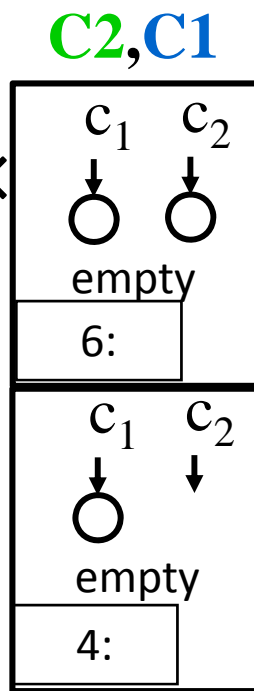
c_2, c_3



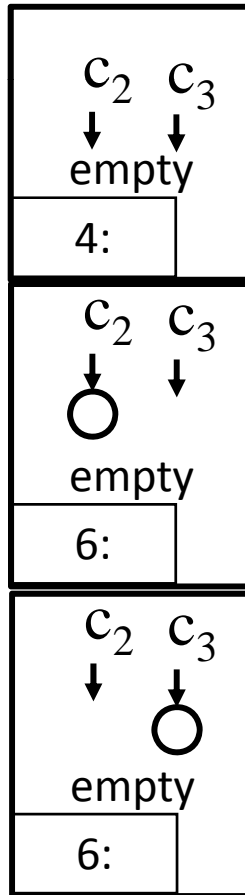
×



×

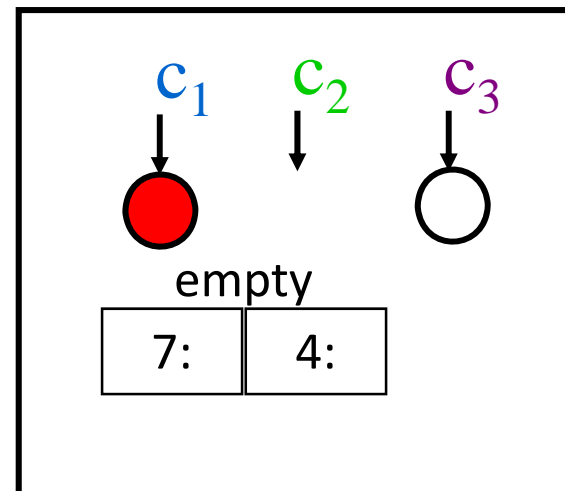
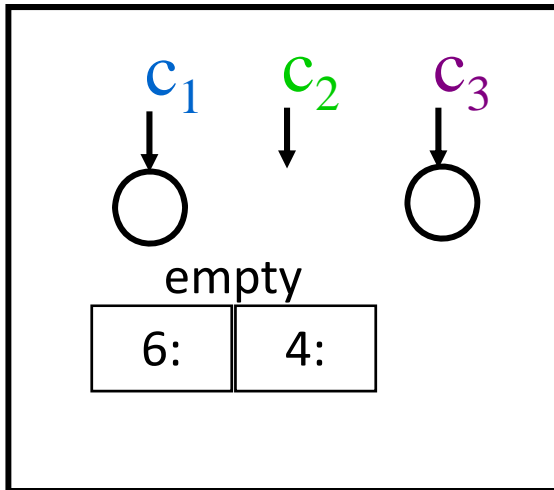
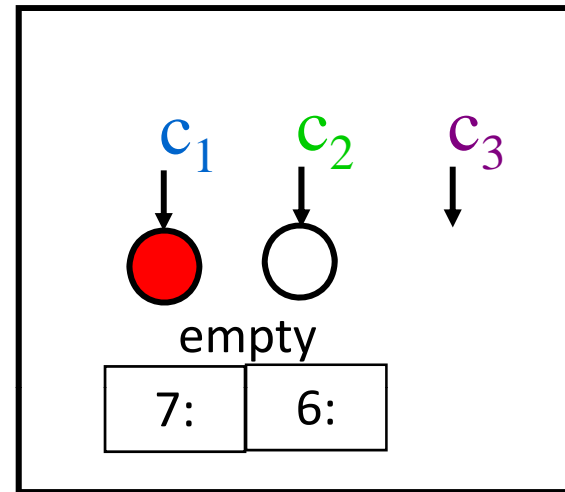
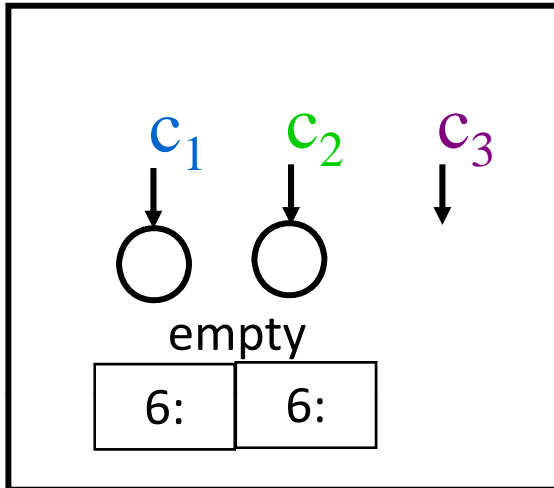


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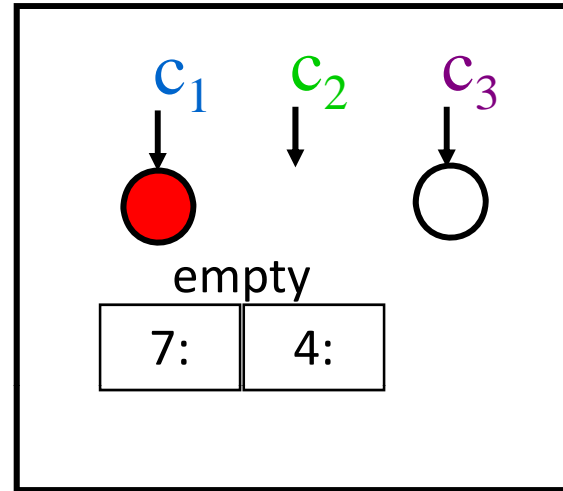
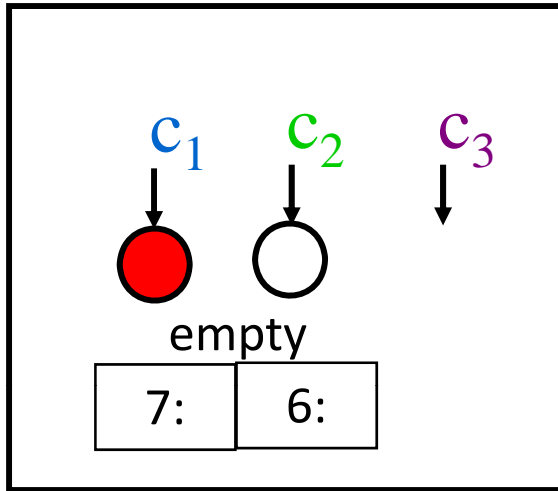


no information on c_4

6: C1: dispose(c) (exec)

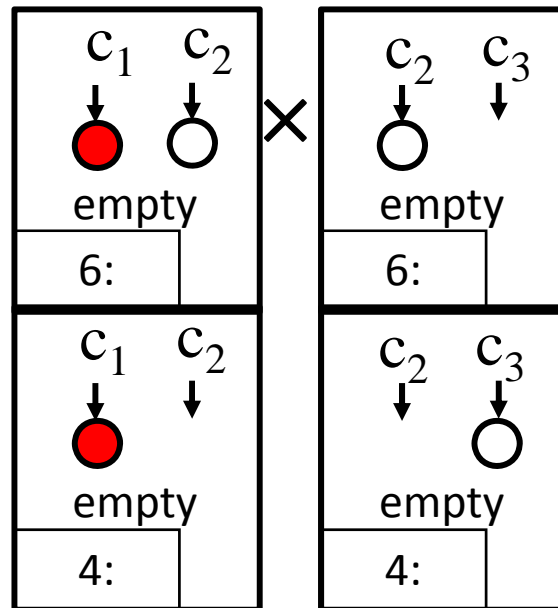


6: C1: dispose(c) (project)



C2,C1

C2,C3

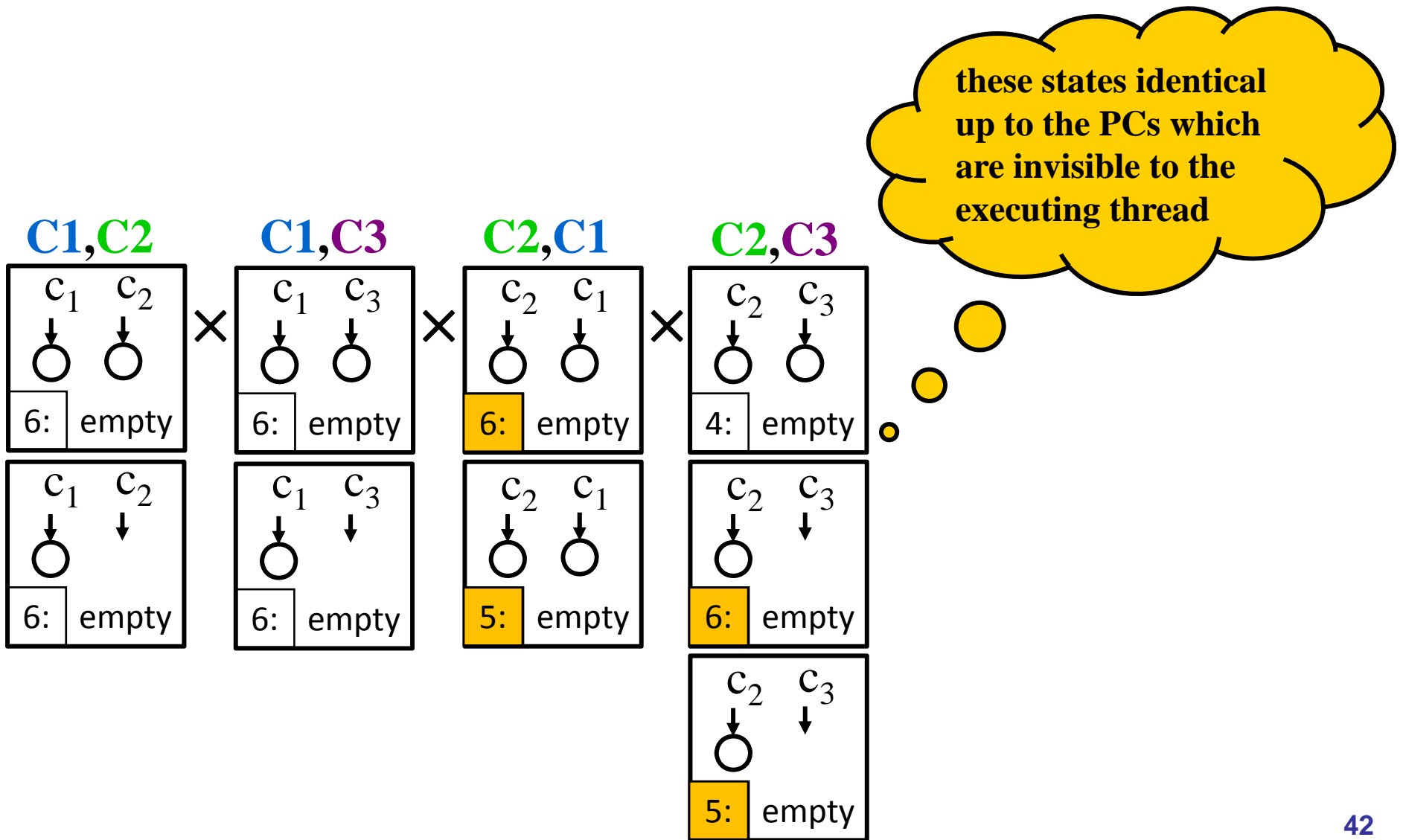


Reducing Quadratic Factors

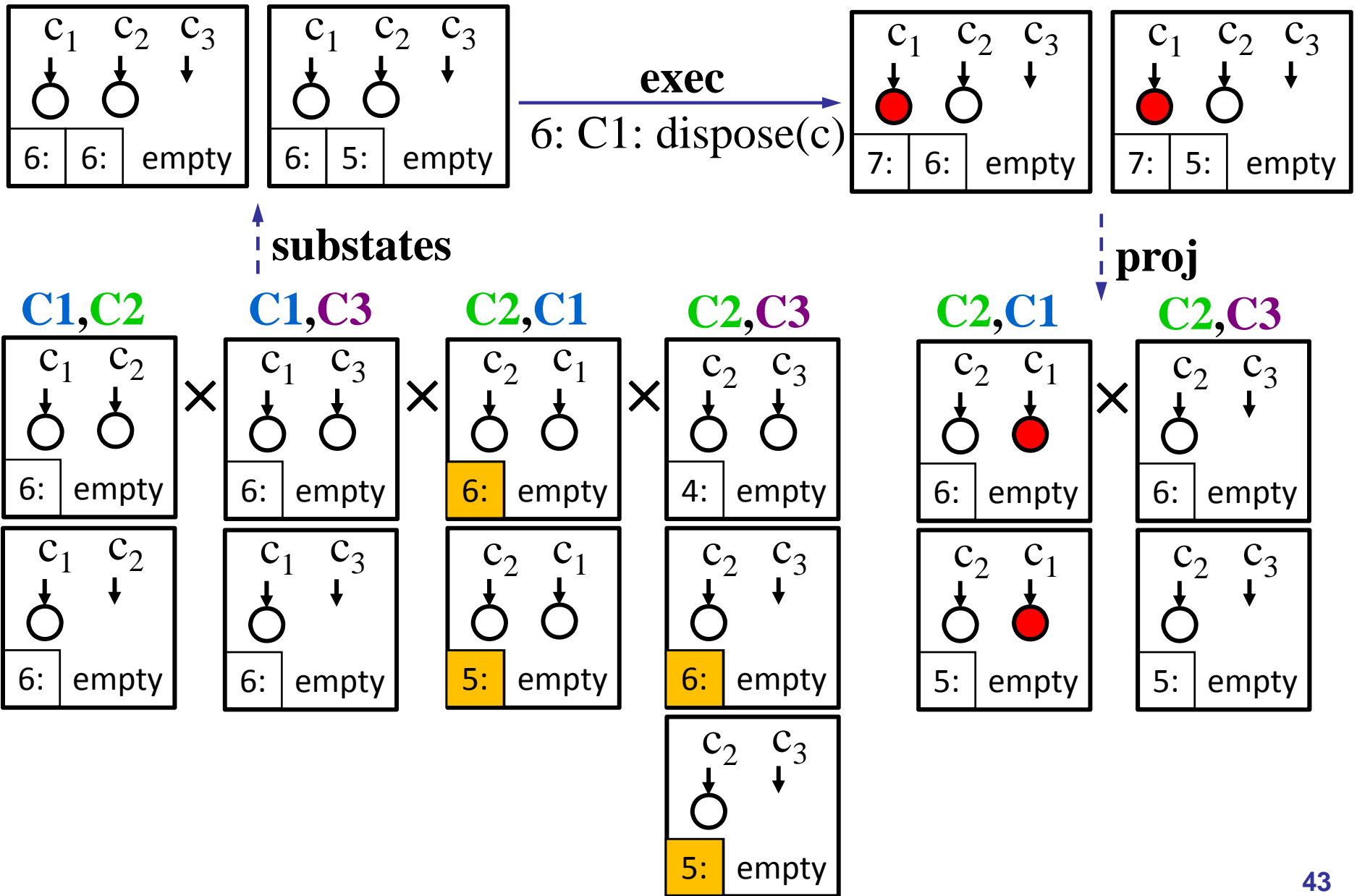
$$\text{TR}(F) = \{ \langle l', g', o \rangle : \langle l, g, o \rangle \in F, \langle l, g \rangle \tau \langle l', g' \rangle \} \cup \left[\begin{array}{l} \langle l_2, g', o \rangle, \langle l_2, g', \alpha(l_1') \rangle : f_1, f_2, f_3, f_4 \in F: \\ \langle l_1, g, l_2, o \rangle \in \text{substates}(f_1, f_2, f_3, f_4), \\ \langle l_1, g \rangle \tau \langle l_1', g' \rangle \end{array} \right]$$

- Exploit redundancies in the action
 - Cannot affect locals of other threads
 - Use asymmetry between the two abstractions
 - Can prove no loss of information
 - **Summarizing Effects**
- Apply aggressive abstraction to the executing threads
 - Potential loss of precision
 - **Summarizing Abstraction**

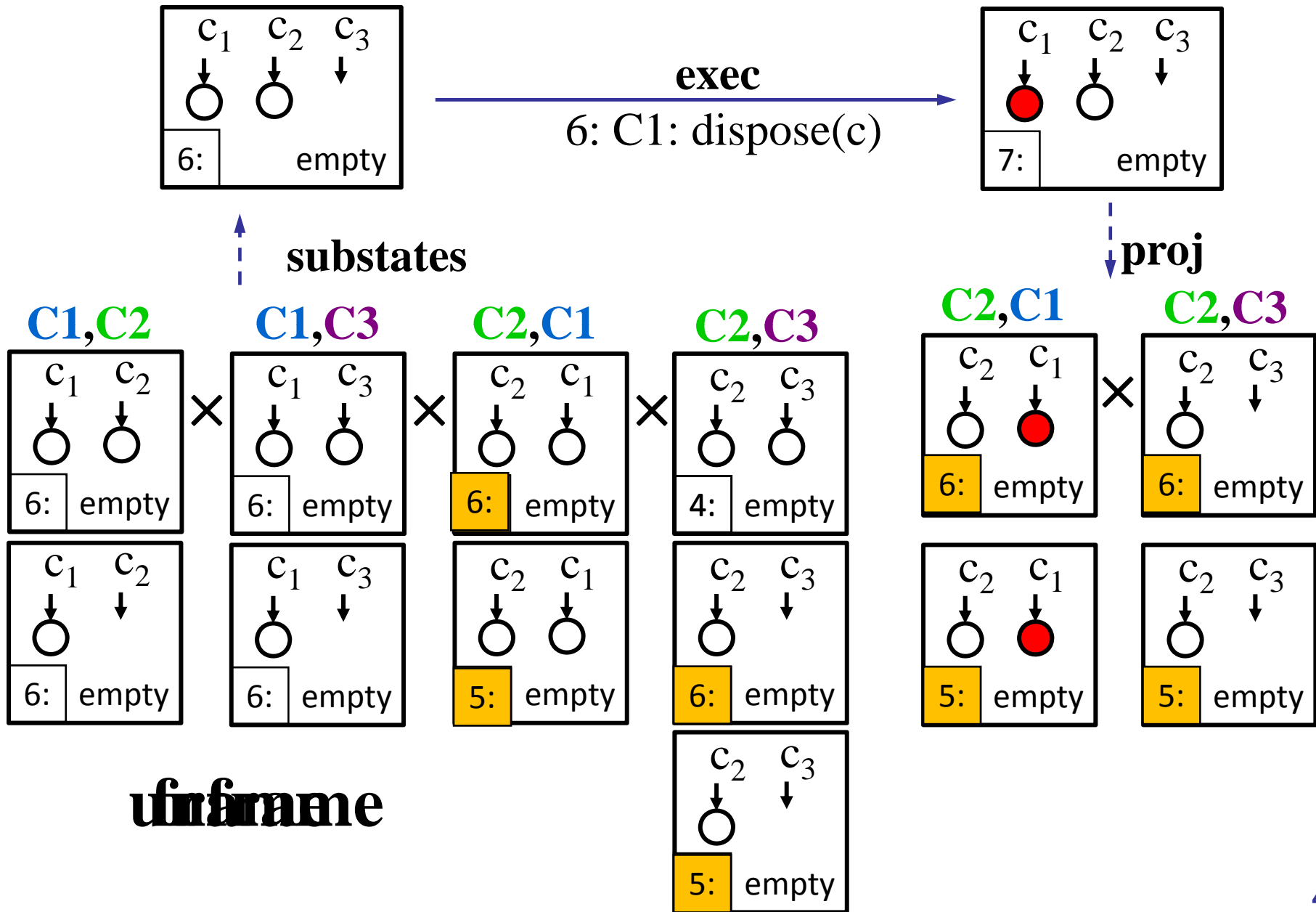
Exploiting Redundancies 6: C1: dispose(c)



Exploiting Redundancies 6: C1: dispose(c)



Exploiting Redundancies 6: C1: dispose(c)



Summarizing Abstraction

$$\text{TR}(\mathbb{F}) = \{ \langle l', g', o \rangle : \langle l, g, o \rangle \in \mathbb{F}, \langle l, g \rangle \tau \langle l', g' \rangle \} \cup \left[\begin{array}{l} \langle l_2, g', o \rangle, \langle l_2, g', \alpha(l_1') \rangle : f_1, f_2, f_3, f_4 \in \mathbb{F}: \\ \langle l_1, g, l_2, o \rangle \in \text{substates}(f_1, f_2, f_3, f_4), \\ \langle l_1, g \rangle \tau \langle l_1', g' \rangle \end{array} \right]$$

- Summarizing Effects reduces the tracked thread's number of states
- Summarizing Abstraction reduces state of executing thread
 - Our heuristic – keep only information accessed by statement
- Significant reduction in size of partial concretization
 - Especially in heap-manipulating programs
 - Precise enough in our benchmarks

A Singleton Buffer - Modified

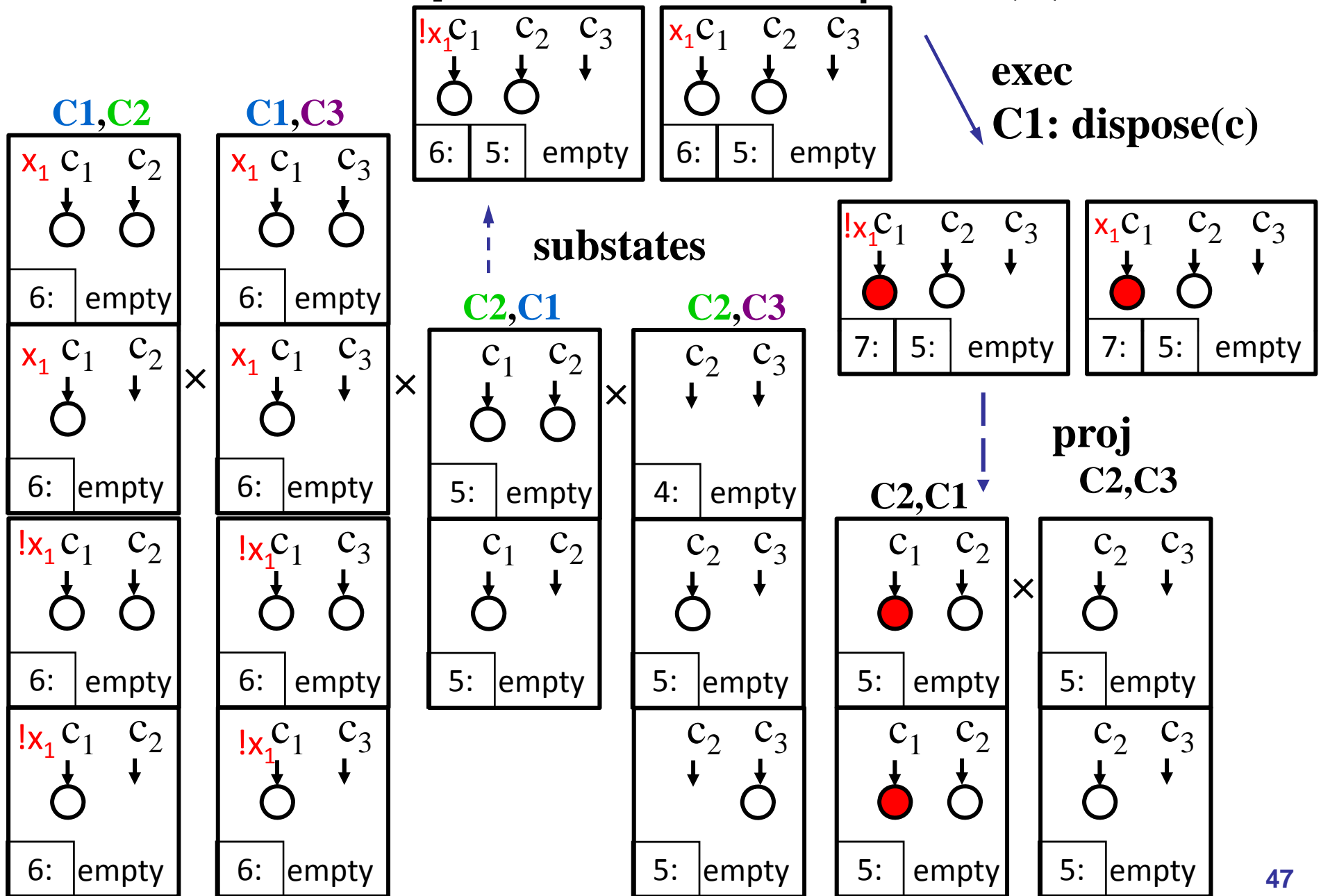
```
Boolean empty = true;
```

```
Object b = null;
```

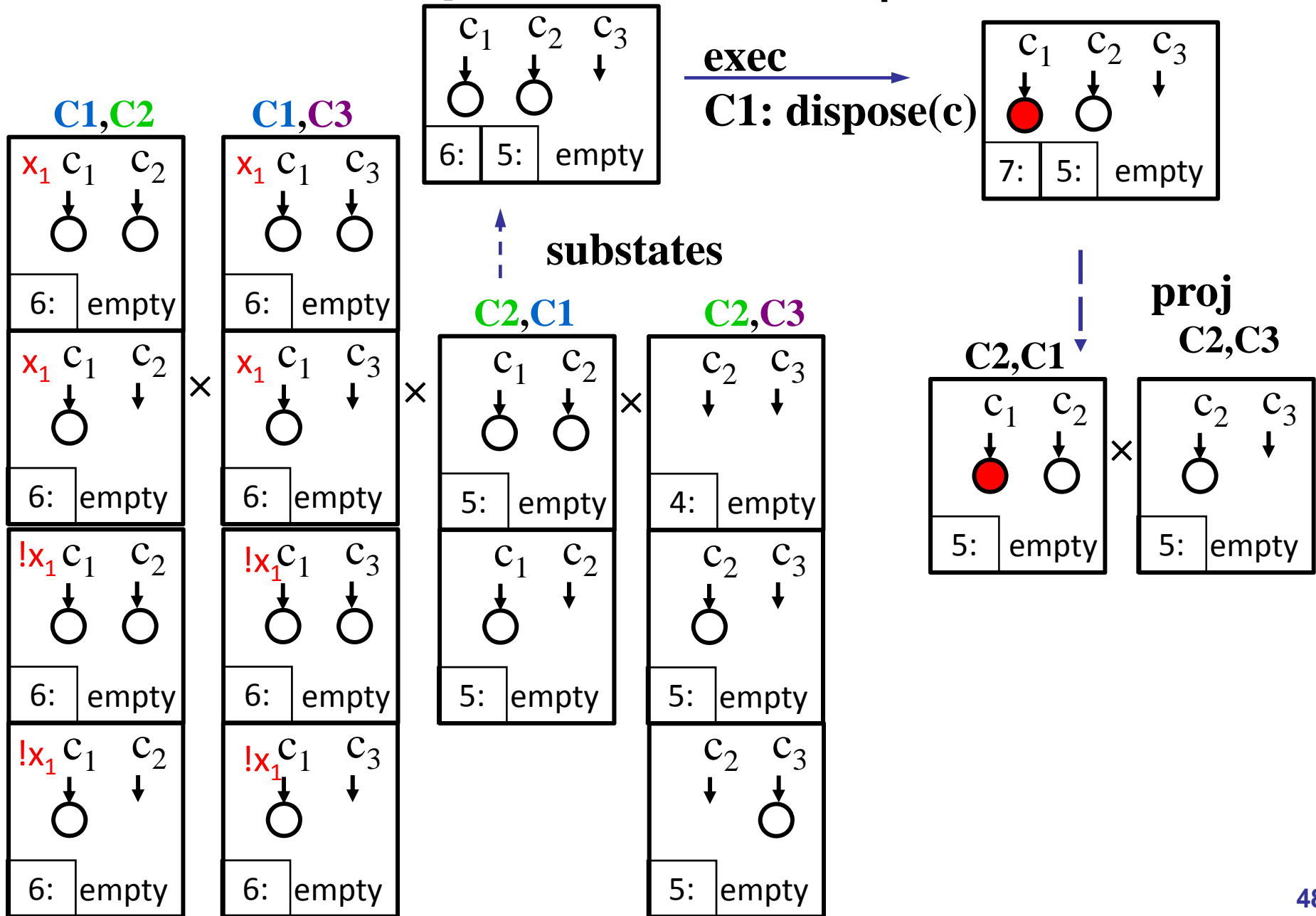
```
produce() {  
  1: Object p = new();  
  2: await (empty) then {  
    b = p;  
    empty = false;  
  }  
  3:  
}
```

```
consume() {  
  Object c;  
  Boolean x;  
  4: await (!empty) then {  
    c = b;  
    empty = true;  
  }  
  5: x = f(c);  
  6: dispose(c);  
  7: use(x);  
  8:  
}
```

Example 6: C1: dispose(c)

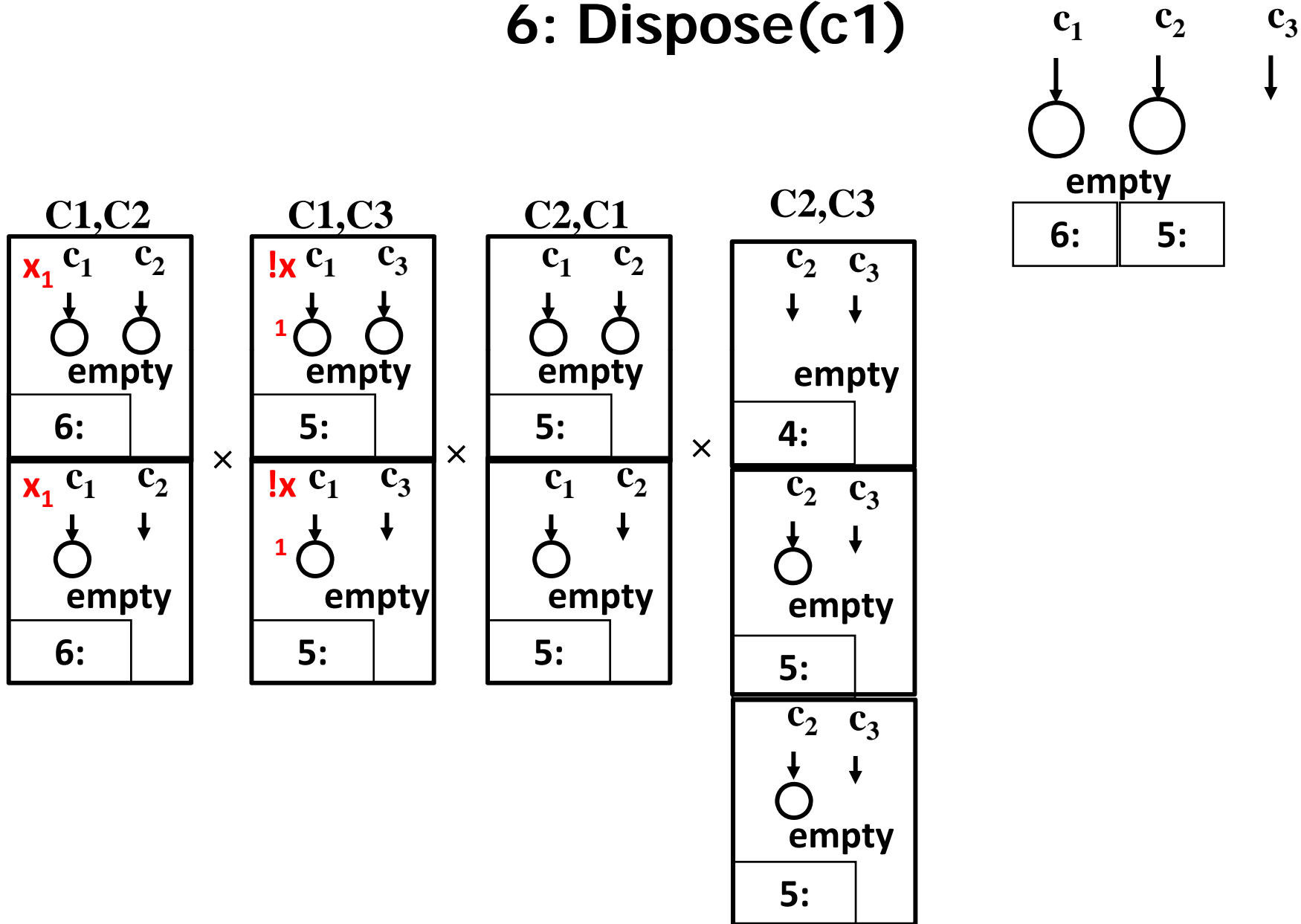


Example 6: C1: dispose(c)



Loss of Precision in Summarizing Abstractions

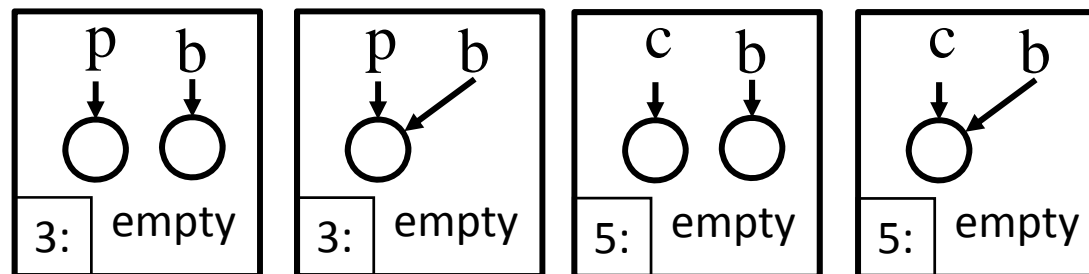
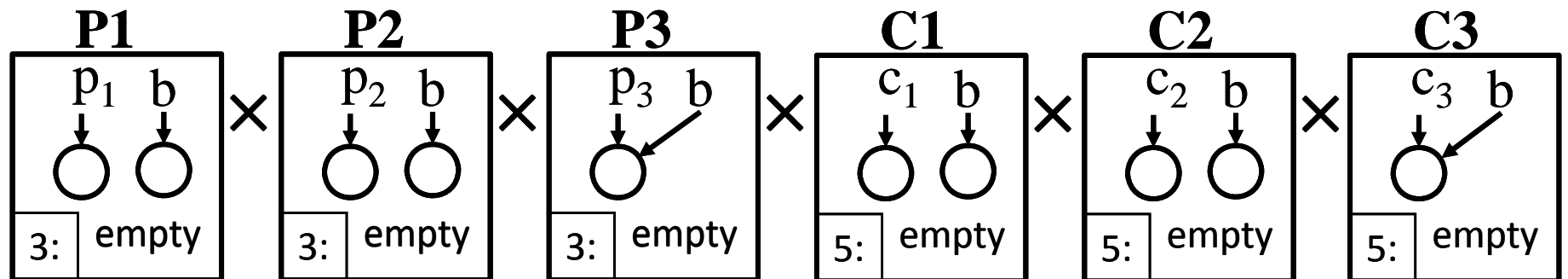
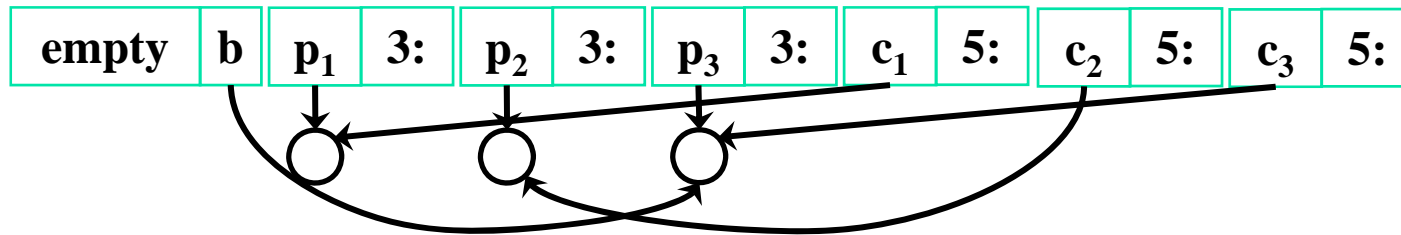
6: Dispose(c1)



Unbounded Number of Threads

- Abstract thread identifiers
- Usually no extra loss of precision
- Universally quantity over threads

Thread-Modular Abstraction for Unbounded Number of threads



Thread-Modular Abstraction for Unbounded Number of threads

$\forall t:$

$(pc(t)=3 \wedge p(t) \neq b \wedge \text{valid}(p(t)) \wedge \text{valid}(b) \wedge \text{empty})$

∨

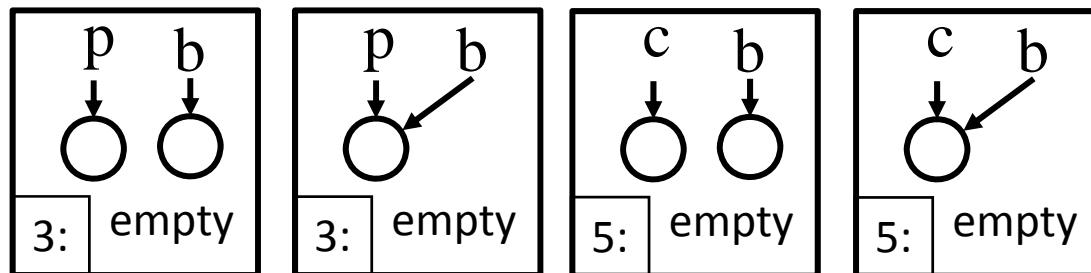
$(pc(t)=3 \wedge p(t) = b \wedge \text{valid}(p(t)) \wedge \text{valid}(b) \wedge \text{empty})$

∨

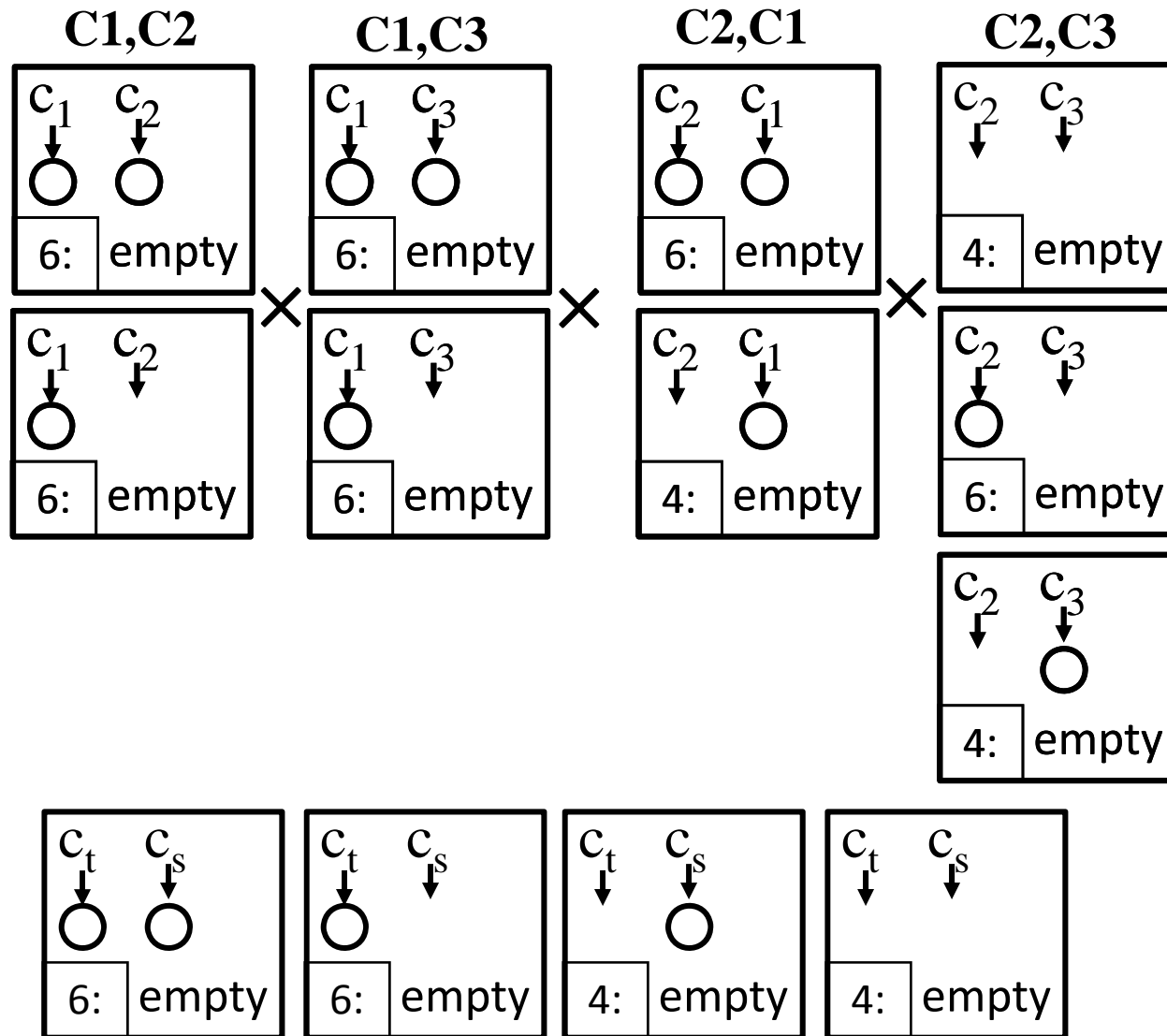
$(pc(t)=5 \wedge c(t) \neq b \wedge \text{valid}(c(t)) \wedge \text{valid}(b) \wedge \text{empty})$

∨

$(pc(t)=5 \wedge c(t) = b \wedge \text{valid}(c(t)) \wedge \text{valid}(b) \wedge \text{empty})$

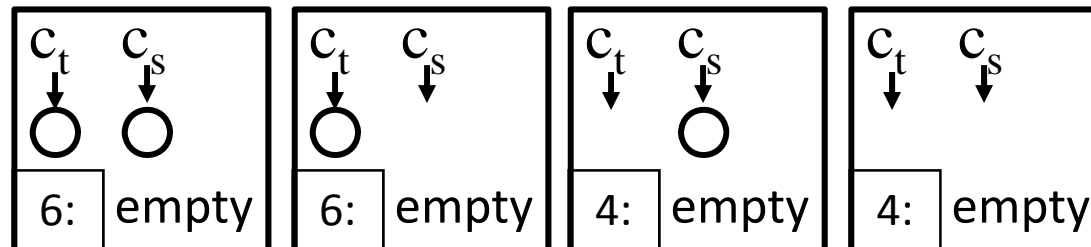


Semi-Thread-Modular Abstraction for Unbounded Number of threads



Semi-Thread-Modular Abstraction for Unbounded Number of threads

$$\begin{aligned}
 \forall t, s: s \neq t \Rightarrow & \\
 & (\text{pc}(t)=6 \wedge c(t) \neq c(s) \wedge \text{valid}(c(t)) \wedge \text{valid}(c(s)) \wedge \text{empty}) \\
 & \vee \\
 & (\text{pc}(t)=6 \wedge \text{valid}(c(t)) \wedge c(s)=\text{null} \wedge \text{empty}) \\
 & \vee \\
 & (\text{pc}(t)=4 \wedge c(t)=\text{null} \wedge \text{valid}(c(s)) \wedge \text{empty}) \\
 & \vee \\
 & (\text{pc}(t)=4 \wedge c(t)=\text{null} \wedge c(s)=\text{null} \wedge \text{empty})
 \end{aligned}$$



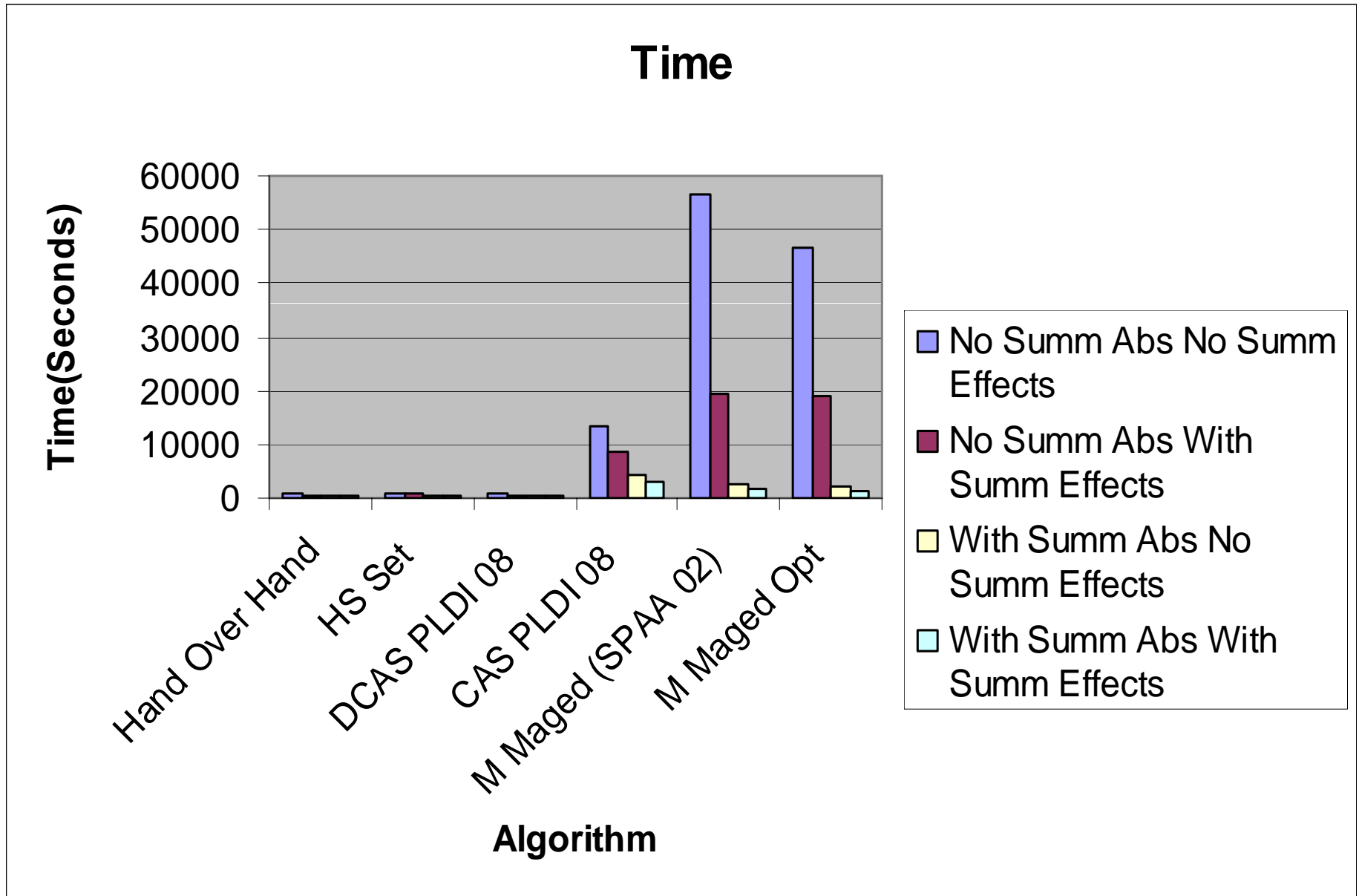
In the TR

- Proofs of soundness
- No loss of precision from summarizing effects
- Combination with heap abstraction
 - Meet is important

Evaluation

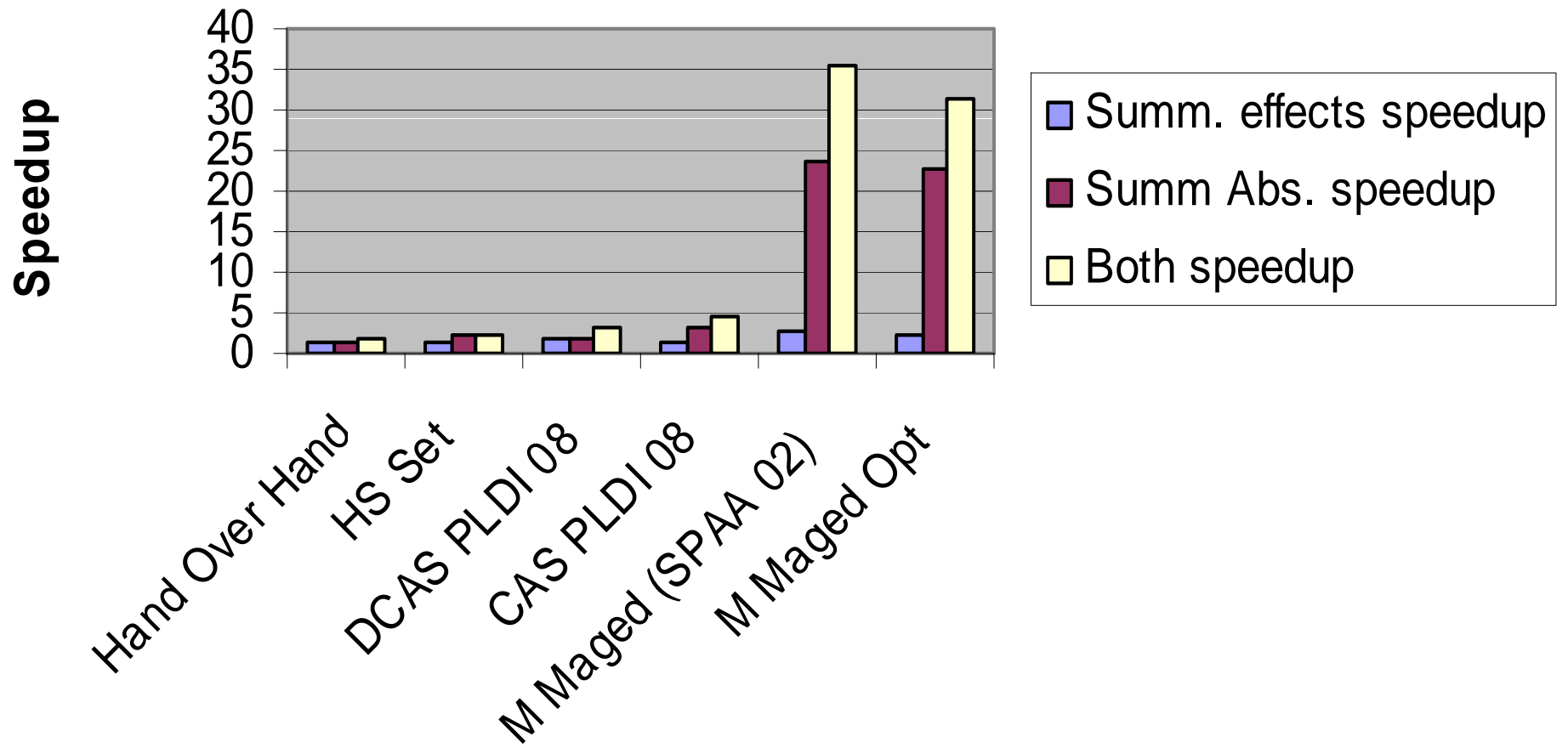
- Implemented (semi-)thread-modular shape analysis using HEDEC/TVLA
 - Unbounded number of threads
 - Unbounded number of objects
 - Call strings for procedures
- Thread-modular unable to prove properties without additional (global) instrumentation
- Semi-thread-modular analysis proves required properties
- Reproduce the injected errors

Evaluation



Evaluation

Speedup



Related Work

- Process centric abstractions
 - [C. A. R. Hoare '72] [Owicki & Gries '76]
[E. Clarke TOPLAS'80] [Talupur et al. VMCAI'06]
[Flanagan & Qadeer, SPIN'03] many more...
 - [Malkis, Podelski, Rybalchenco, SAS'07]
- Thread-modular shape analysis
 - [Gotsman et al. PLDI'07]
 - [Manevich et al. SAS'08]
 - [Calcagno et al. SAS'07]
 - R-G reasoning [Vafeiadis et al. '06-'09]

Summary

- A new abstraction for concurrent systems
 - Scalable in the number of threads
 - Handles unbounded number of threads
 - Semi-thread-modular program analysis
- Provably sound analysis
- Potential loss of precision
 - Abstraction
 - Transformers
 - But precise enough – 0 false alarms
- Reducing quadratic factors